

Scaling Characteristics of Modelled Tropical Oceanic Rain Clusters

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Abstract

The scaling exponents of the distributions of cluster rain amount, R , and cluster size, A , for oceanic rain clusters over the Indian and Pacific warm pools, and the intertropical convergence zones over the eastern Pacific and the tropical Atlantic, were obtained from a set of regional climate model downscaling products. The main aim of the investigation is to compare the model cluster's scaling characteristics with those obtained from observations that have been reported previously. The scaling exponents for the model were found to be different across the ocean basins indicating the lack of universality in the modelled rain cluster distributions. The scaling exponent for the conditional mean of R given $A = a$, $E(R|a)$, was found to be the same across the different ocean basins, and the estimated value of the exponent agrees with that obtained from satellite observed rain clusters. However, no crossover in the scaling of $E(R|a)$ in the model for cluster size larger than mesoscale was seen, unlike those reported elsewhere based on observations. The implication is that in the model the intensification of rain with cluster size continues up to synoptic scale. Through simple scaling arguments it is believed that before the break in scaling that has been identified from an observational study elsewhere, the model simulates the fundamental mesoscale dynamics well and thus estimated the $E(R|a)$ in agreement with observations. Whether such difference in transition of scaling between the modelled and observed rain cluster scaling behaviour depends on the model details, for example the convection parameterization needs further clarifications.

1. Introduction

Several investigations have demonstrated that deep convective rain possesses universal behaviour across the different tropical ocean basins and as a result, the probability distributions of the rain clusters, when suitably normalized are identical (Peters and Neelin, 2006; Peters *et al.*, 2009; Teo *et al.*, 2017). One approach to explain how such universality can arise is to appeal to the hypothesis that tropical deep convective rain is a self-organised criticality (SOC) among the other models (Traxl *et al.*, 2016). Such a view was first forwarded by Andrade *et al.* (1998) and then more formally proposed by Peters and Neelin (2006) where they pointed out that the tropical convective atmosphere has the following ingredients for SOC: 1) the existence of a column water vapour content threshold beyond which the convective rain intensity increases exponentially; 2) the clear separation of the relaxation (convective) time scale and the driving time scale of the (relatively slower) build-up of the atmospheric water vapour content from the latent heat fluxes from the ocean surface and large scale moisture advection.

It has been proposed that the ubiquitous presence of deep convective rain clusters of a wide range of spatial scales over the tropical oceans is yet another aspect of the tropical convective rain as an SOC (Peters and Neelin 2006; Neelin *et al.* 2008; Teo *et al.* 2017; abbreviated as T17 hereafter). T17 suggested that the rain clusters are analogous to avalanching sandpiles – the archetypal SOC model (e.g. Bak *et al.*, 1987), with the rain cluster size, A , and the cluster rain amount, R (total rain intensity over the cluster area), corresponding to the avalanche area and avalanche size of a critical sandpile. The probability density distributions for both A and R are by virtue of being a SOC assumed to follow simple scaling (Christensen and Moloney, 2005 p. 273):

$$f_S(s) \sim s^{-\zeta_S} \mathcal{G}_S\left(\frac{s}{s_c}\right), \quad s > s_0; \quad S \in \{A, R\} \quad (1)$$

where $f_s(s)$ is the probability density distribution, ζ_s is the scaling exponent, and $\mathcal{G}_s$ is the scaling function expressing the departure from a strict power law due to the finite size of the system (the oceanic domain where these tropical mesoscale rain clusters organise; see Fig. 1). This scaling function $\mathcal{G}_s(y)$ has the following property: it decays faster than a power law for $y \gg 1$, and stays (almost) as a constant for $y \ll 1$. Hence the probability distribution exhibits a strict power-law regime ($f_s(s) \sim s^{-\zeta_s}$) only for values of s larger than the lower cutoff, s_0 , but much smaller than the upper cutoff, s_c . For simple scaling to be valid, the upper cutoff, s_c , increases monotonically with the system size, while the lower cut off, s_0 , is independent of the system size. By analysing the distributions of satellite observed rain clusters over oceanic tropical rain clusters, T17 concluded that the tropical oceanic rain clusters are universal (i.e., consistent across the ocean basins) with the scaling exponents, ζ_A and ζ_R being $5/3$ and $3/2$ respectively. T17 also found two scaling regimes for conditional mean of R given $A = a$, $E(R|a)$ from the observed rain clusters: for a rain cluster of length scale smaller than ~ 320 km, $E(R|a) \sim a^{4/3}$. For cluster with length scale larger than 320 km, $E(R|a)$ was proportional to a . They suggested that such scaling behaviour could mean that rain clusters tend to grow or decay non-linearly below 320 km while larger clusters of size beyond 320 km grow into or decay from superclusters without intensification.

Model evaluation based on scaling of the modelled variables has been emerging (e.g., Skamarock, 2004; Kahn et al. 2011; O'Brien et al. 2013; Fang and Kuo 2015). In this work, we analysed the scaling characteristics of oceanic tropical rain clusters from a regional climate model. The main questions we wish to address in this work are: 1) whether the distributions of the model rain clusters are universal across all the ocean basins; 2) whether the model can reproduce the same scaling behaviour as what has been observed for actual rain clusters. The resulting analyses serve as a set of diagnoses for the self-organizing behaviour of model rain clusters in the tropics.

Increasingly, multiscale interactions are recognised to be an important aspect of the dynamics of tropical weather systems from mesoscale convective complexes and synoptic-scale convectively coupled equatorial waves, up to planetary scale systems like the Madden Julian Oscillation (e.g. Nakazawa, 1988; Tulich and Mapes, 2008; Kiladis *et al.*, 2009; Biello and Majda, 2005). Therefore, diagnoses that encapsulate the scaling behaviour of rain clusters, such as those presented in this work, are indicative of the model's performance in the tropics.

At the same time, investigating scaling behaviour of rain clusters from the model may be a step towards identifying the essential mechanisms that explains the emergence of SOC in the self-organisation of tropical rain clusters. Besides the model proposed by Stechmann and Neelin (2014) for the temporal rain clusters that exhibited SOC, the spatial extension of a similar model in Hottovy and Stechmann (2015) and the physically based stochastic model in Ahmed and Neelin (2019), the authors are not aware of any other physically based SOC model that accounts for the system size distributions of self-organizing deep convection clusters. Obtaining a representative set of scaling exponents of the model rain cluster distributions is therefore a useful first demonstration of similar analyses of rain clusters from different model physics configurations or from various other models, such as those from Quinn and Neelin (2017a, b). Ideally, some current or future meteorological models or model physics configurations ought to reproduce the observed scaling exponents and shed light on the actual physical-dynamical mechanisms that give birth to SOC behaviour in tropical rainfall. This would facilitate the understanding of SOC in tropical rainfall away from the conventional representations of SOC which are mostly “toy” mathematical representations not based on the universal laws of physics.

The remainder of the paper is as follows: Section 2 outlines the model products used and how the rain clusters were obtained. Section 3 describes how the cluster probability density

distributions were estimated and reports on their general characteristics. A more detailed analysis of the scaling exponents of the model rain clusters is in Section 4. Further remarks and discussions on the implications of our findings are in Section 5 before concluding in Section 6.

2. Data and processing

Twenty-eight years of gridded three-hourly model rainfall accumulation from April 1988 – March 2015 produced with the Weather Research and Forecasting model (WRF; Skamarock *et al.*, 2008) were made available for this investigation. The rainfall is the sum of the rainfall from the cloud microphysics scheme and the parameterized cumulus convection. A brief description of the model is summarised below. Details of the model configurations and model performance can be found in Fonseca *et al.* (2019).

The model domain was a tropical channel confined within 36°S – 40°N. The horizontal resolution of the model was 36 km, with 37 vertical levels up to 30 hPa that were spaced more closely together in the planetary boundary layer (PBL) and the tropical tropopause layer. The model was initialized with Climate Forecast System Reanalysis (CFSR; Saha *et al.*, 2010) 6-hourly data. Analysis nudging of several model fields towards the CFSR values was applied in the model runs (Fonseca *et al.*, 2019): the model horizontal winds and potential temperature perturbations were nudged in the lower stratosphere to provide observed upper boundary conditions associated with the Quasi-Biennial Oscillation (Andrews *et al.*, 1987), while the water vapour mixing ratio was nudged in the mid-troposphere to maintain a close correspondence to observed tropical moisture distribution in the model runs, each of uninterrupted one-year duration, for a good simulation of the Madden-Julian Oscillation (Ulate *et al.*, 2015). The latter point is important for this study because we are interested in capturing real-world and not just realistic-looking rainfall

patterns at mesoscale resolution. The nudging timescale was set uniformly to 1 h wherever nudging was applied.

With the help of a first-order ordinary differential equation, it is straightforward to demonstrate that nudging works only in constraining the model climatology. At sub-seasonal and synoptic timescales, nudging exerts net zero impact on tropospheric water vapour mixing ratio because the reference CFSR field itself is varying on the same 1-h timescale as the nudging process. (Nudging in this case can be compared to chasing after a fluttering butterfly: only the long-time tendency can be followed effectively.) On those temporal scales and the associated spatial scales, the model is practically free to vary in the mid-troposphere while the planetary boundary layer is not nudged at all. The interested reader is referred to the supplementary material of Fonseca *et al.* (2019) showing that the nudging tendency of water vapour mixing ratio is globally much smaller than the largest term in the precipitable water budget. But nudging is necessary to correct for the positive bias in the climatology of evaporation from subtropical ocean surfaces in the model. The resulting model tropical rainfall is well-verified with observations on sub-seasonal and synoptic timescale as shown in Fonseca *et al.* (2019).

Grid-resolved cloud processes were based on the Goddard six class microphysics scheme (Tao *et al.*, 1989). Sub-grid scale cumulus clouds were parametrised using the Betts-Miller-Janjić scheme (Janjić, 1994) but adapted for the tropics (Fonseca *et al.*, 2015), including a precipitating convective cloud scheme to account for the cumulus cloud-radiation feedback (Koh and Fonseca, 2016). The Rapid Radiative Transfer Model for Global (RRTMG) model was used for computing the short-wave and long-wave radiation (Iacono *et al.*, 2008), and the Yonsei University PBL scheme (Hong *et al.*, 2006) was used with Monin-Obukhov surface layer parametrisation (Monin and Obukhov, 1954). An interactive prognostic scheme for the sea surface skin temperature

(SSKT) based on Zeng and Beljaars (2005) was used in the model to capture the diurnal variation of the SSKT and allowed its feedback to the air temperature, moisture and radiation fields. The lower boundary condition to the SSKT-scheme came from the 6-hourly SST data from CFSR, linearly interpolated in time in order to have a continuously varying thermal constraint on the ocean skin layer.

We are interested in estimating the scaling exponent of the distributions for the cluster area (A) and cluster total rain rate (R). In a given three-hourly time-slice of the gridded model rain product, a single rain cluster was identified as a set of rainy grid pixels with area of ΔA (the representative area of a model grid point, which was roughly constant about $36 \text{ km} \times 36 \text{ km}$) sharing a common border with at least one of its nearest-neighbour rainy grid pixels. The rain area, A in units of ΔA , is the count of rainy grid pixels of the cluster. The total rain rate, R in units of $\Delta A \text{ mm/hr}$ (roughly $360 \text{ m}^3/\text{s}$), is the sum of the rain intensity at all the grid pixels of the cluster. The procedure in data treatment to obtain the distributions of A and R follows closely with that detailed in T17. We refer the readers to Appendix A and Fig. S1 for the details in the procedure involved and only highlight here any procedural modifications or departures from T17 when applied to the present analysis.

Four square focus regions of side $Z = 96$ grid pixels over the Indian (IO) and the western Pacific warm pool (WP) as well as the inter-tropical convergence zones (ITCZ) in the eastern Pacific (EP) and tropical Atlantic (AO) were identified for analyses (Fig. 1). These regions containing deep convection were selected to match as closely as possible the focused regions used in T17 (their Fig. 1). Since the rain clusters found in these regions usually can last for more than three hours, many of the rain clusters within a domain for two consecutive three-hour time-slices

were not independent. Following T17, we estimated the de-correlation time for the rain clusters for IO, WP, EP and AO to be 9, 6, 8 and 5 days.

Each of the 96×96 domains covering the focus regions was further divided into non-overlapping domains of side $Z = 48, 32$ and 24 respectively (Figs. 1 b – d) to account for the dependence of the scaling exponents with the domain size. As land and coastal regions have the potential of organizing rain systems at spatial scales that are determined by the geometry of the coastline and topography, we excluded domains with more than 10% of the area occupied by land.

As our primary interest is in the scaling characteristics of rain clusters arising from convective self-organisation, not all the remaining oceanic domains were used for analysis: some regions like the AO and EP have large swaths of area in which rain arises predominantly from marine stratiform clouds. In our work, we admitted a $Z \times Z$ domain for subsequent analyses only if

$$Q(Z; \varepsilon) > Q_0 \quad (2)$$

where Q_0 is a prescribed positive number less than unity (see below) and the statistic Q is a measure of the coverage of convective rain for the domain, defined as

$$Q(Z; \varepsilon) \stackrel{\text{def}}{=} \frac{1}{NZ^2} \sum_{i=1}^N \sum_{j=1}^{Z^2} \mathcal{H}(p_{ij} - \varepsilon) \quad (3)$$

where N is the number of 3-hourly time-slices when there is rainfall somewhere in the domain; p_{ij} is the ratio of rainfall from the convective parameterisation to the total rainfall both from the convective and microphysics parameterisations at the j^{th} grid point in the i^{th} time slice; ε is a prescribed threshold convective fraction of rain (a positive number less than unity); and $\mathcal{H}(k) = 1$ if $k > 0$ or $\mathcal{H}(k) = 0$ otherwise. Q takes into account both the relative contribution of convective (parameterized) rainfall and the frequency and areal coverage by convective rainfall in a domain. The frequency distribution of Q values encountered across all ocean basins and domain sizes for a given ε (not shown) were found to be bimodal with a minimum around $Q = 0.4$. The peak of the

distribution at $Q < 0.4$ was related to the predominance of shallow convection over EP and AO, while the peak of the distribution at $Q > 0.4$ was due to deep convection clusters. The frequency distributions of Q were also fairly robust for a broad range of values of ε tested. We therefore adopted a value of 0.4 and 0.8 for Q_0 and ε respectively.

Figure 1 shows the domains accepted and rejected for the various values of Z . The 96x96 domains for EP and AO were excluded because the convective regions are confined within a narrow latitudinal band where the model ITCZ was located (c.f. the accepted domains for $Z = 48, 32, 24$). As the original four 48x48 AO domains were rejected by our criteria due to the ITCZ being split almost equally among them, we added two additional 48x48 domains containing the ITCZ (heavy solid box in Fig 1b for $Z = 48$) that satisfy our selection criteria.

We partitioned the cluster area and rain data for all focus regions into 40 non-overlapping temporal data subsets each containing the cluster information for a fixed Coordinated Universal Time (00 UTC, 03 UTC, ..., 21 UTC) with a sampling interval of their respective cluster decorrelation times already mentioned above. The major differences in the details of our analysis method applied here compared with those in T17 have been summarized in Appendix A.

3. Probability distributions

For each focus region, the ensemble mean probability distributions of A and R for all domains of a fixed size $Z \times Z$ were obtained separately in each of the 40 non-overlapping temporal data subsets. This ensemble comprised only those $Z \times Z$ domains that passed the selection criteria described in the preceding section (Fig. 1). Thus, the ensemble members can be considered independent realisations of a true probability distribution, although the 96x96 domains for IO and WP form only single-member ensembles.

Figure 2 shows the average of the 40 (correlated) ensemble mean probability distributions for A and R for WP for different Z . Unlike the observed cluster area and rain distributions reported in the literature, which monotonically decrease with increasing A and R (c.f. Fig. 3 in T17), the model cluster distributions show obvious “bumps” or rapid increase at large A and R . This feature was present for the A and R distributions in the four focus regions across the global tropics. These bumps or sharp increases in the probabilities were the result of the model’s tendency to form a continuous zonal rain band spanning across the domains including the largest 96×96 domains which are approximately 30° in extent. This suggests that tropical deep convection in the model tends to be overly organised by planetary scale processes most of the time. Therefore, for all domain sides Z in the subsequent analysis, we consistently excluded clusters that span across either the east-west sides or north-south sides of a domain, thereby assuring ourselves that we are studying rain clusters that were likely to be self-organised through local processes in the model. The distributions for A and R with these spanning clusters excluded (Fig. 3) are monotonic (for all a and for $r > 0.1$) and the distributions decay faster than power-law behaviour at large values of A and R in line with observations (e.g. Fig. 3 of T17). Henceforth, all reference to the cluster distributions refer to the mean ensemble distributions obtained by excluding any east-west domain-spanning clusters.

From Fig. 3a, the distributions for A for all domain size appear to follow simple power-law scaling beyond $a \sim 10\Delta A$, though we note that the scaling regime even for the largest domain size ($Z=96$) seemed to span at most only one order of magnitude. The distribution for R is more complicated. For very small values of R ($\lesssim 10^{-4} \Delta A$ mm/hr), the distribution is highly variable (Fig. 3b). It was found that most of these light rain events were associated with clusters at the limit

of model resolution ($a = 1$) and the high variability in the R distributions is due to the discretization of the very light rain produced by the cloud microphysics and the cumulus parameterisations.

Unlike the case for A , it is more difficult to discern a power-law regime visually for the distribution for larger R ; the steepening in the gradient of the distribution around $r \sim 0.5 \Delta A$ mm/hr is gradual and a power-law regime is not easily discerned for domains with $Z < 96$ from the plot (Fig. 3b). However, we proceed to assume a simple scaling ansatz for the distribution of R (for large enough R) since it is possible that the magnitude of the upper cutoff, r_c , where the finite system size starts deviating from the strict power law is relatively small (compared to r_0 , the lower cutoff where simple scaling ansatz are valid; see Equation 1) making it difficult to discern a clearly defined scaling regimes within the available domain size. Moreover, the observed distribution of R over the same oceanic domains exhibited simple scaling (T17) and hence it is not unreasonable to use simple scaling for R *a priori*.

4. Scaling exponents

4.1 Exponent for the probability distributions

For each focus region, the scaling exponents for both the A and R distributions for the different $Z \times Z$ domains were estimated by fitting the cluster ensemble distribution to a distribution model

$$f(s) = C_s s^{-\tau_s} \exp \left[\left(\frac{s}{s_c} \right)^{\nu_s} \right], s \geq s_0 ; S \in \{A, R\} \quad (4)$$

where $f(s)$ is the (discrete) probability for the case when S is A (measured in ΔA), or the probability density function for the case when S is R (measured in ΔA mm/hr); C_s is a normalization constant; and τ_s , ν_s and s_c are distribution parameters determined using the Method of Maximum Likelihood for a prescribed s_0 , labelled as a_0 and r_0 respectively for A and R . In this work, we selected six a_0

approximately separated by regular logarithmic intervals from 10 to 50. Similarly, six r_0 at regular logarithmic separations from 0.5 to 5 ΔA mm/hr were selected. We obtained one estimate of the scaling exponent, $\tau_S(Z; s_0)$, $S \in \{A, R\}$, from each of the forty ensemble distributions computed from the cluster data subsets (see above). The best point estimate of τ_S for each Z and S_0 was then obtained from these forty $\tau_S(Z; s_0)$ estimates following T17.

Visual inspection of the plots of the scaling exponents versus the reciprocal of the domain size Z , suggested that there is a dependence of the scaling exponents with the domain size in which the clusters were identified, for IO, WP, EP (Figs. 4a – c). Such a dependence can also be discerned from the slopes of the near-linear segments in the plots of the probability distributions of A and R for the three focused regions (c.f. Fig. 3). Following T17, we estimated ζ_S as the thermodynamic limit of τ_S (i.e. $\zeta_S = \lim_{Z \rightarrow \infty} \tau_S$) using the intercept of a robust linear regression with Huber weights of the point estimates of $\tau_S(Z; S_0)$ with $1/Z$ as in T17 (Figs. 4 a – d). All the regressions for the focus regions were significant (p-value < 0.05) except for AO. Fig. 4e shows the estimated ζ_S and their values are tabulated in Table 1. These scaling exponents identified in this study are compared with the corresponding values in the four ocean basins in T17 (Appendix B and Fig. S2).

4.2 Scaling exponent of conditional mean of R

For each focus region and each domain size Z , the sample estimates of $E(R|a)$, the conditional mean of the cluster rain amount given the cluster area $A = a$, were calculated from each of the 40 data subsets. For a given Z , the conditional mean was computed from the clusters within those domains that passed the selection criteria described in Section 2. Figs. 5a – d show the double logarithmic plots of the $E(R|a)$ versus a for the statistics from one of the subsets for IO for the different domain sizes, which strongly suggest that $E(R|a)$ has a power-law scaling. Such scaling

has also been reported in T17 for the observed oceanic rain clusters. Fig. 5 is fairly representative of the $E(R|a)$ for clusters from the remaining data subsets as well as for other focus regions. T17 reported that the observed $E(R|a)$ have two scaling regimes, with rain clusters smaller than length scale of ~ 320 km having an exponent of $4/3$ and larger clusters having $E(R|a)$ proportional to the rain cluster size. In contrast the $E(R|a)$ from the model did not have any discernible transition in its scaling exponent (c.f. Figs. 5a – d). Note that a rain cluster of length scale ~ 320 km is about $79 \Delta A$ in our model configuration lying mid-range in Figs. 5a – d. Hence, we adopted a simpler model than T17:

$$E(R|a) = ka^b \quad (5)$$

where k and b are positive numbers to be determined. For each focused region, an estimate of the scaling exponent b was obtained from each data subset via a linear regression of $\log E(R|a)$ against $\log a$. The procedure of estimating b was repeated for all Z and a representative $b(Z)$ was subsequently determined as the sample mean of the 40 separate b estimates. Separate b values were estimated for each Z in anticipation of a functional dependence of b with Z as in the case of ζ_s . There were no $b(Z=96)$ estimates for EP and AO however, as the 96×96 domains for both focus regions did not pass the selection criteria described in Section 2. However, the p-values of the linear regression of the $b(Z)$ against $1/Z$ (not shown) as in the preceding section were greater than 0.05 for all focus regions, providing no significant evidence that the exponent b depends on Z . As such, we estimated the scaling exponent as the sample mean $\hat{\beta}$ of the available $b(Z)$ (Fig. 5e and Table 1).

As a consistency check, from the scaling relation in T17,

$$\hat{\beta} = \frac{1-\zeta_A}{1-\zeta_R} \quad (6)$$

another estimate $\hat{\beta}$ of the scaling exponent for $E(R|a)$ against a was computed for each ocean basin using the currently estimated ζ_A and ζ_R . Except for the near-miss in EP, $\hat{\beta}$ of all ocean basins practically agree within error bounds with β directly obtained from the scaling of $E(R|a)$ described earlier (see Table 1). This is true because equation (6) is derived from statistical arguments alone.

Our results for β in Fig. 5e are consistent with the view that the scaling exponent is the same within the error bounds across all the ocean basins, although we note the relatively large uncertainty in the estimate for AO. One estimate for a representative value for all the oceans is taking the mean of the individual estimates which gives $\bar{\beta} = 1.36 \pm 0.05$. We include AO in the computation because, notwithstanding the lower than 95% confidence level for ζ_A , ζ_R and hence $\hat{\beta}$ estimates in AO, this focus region shows the same insensitivity of the b estimates with domain size Z as the other focus regions. Hence, despite the differences in ζ_A and ζ_R across the ocean basins, we think that β is the same across all the ocean basins. Furthermore, the estimate of $\bar{\beta}$ is the same within estimation errors as the observed β value of 1.33 ± 0.03 reported in T17.

5. Further discussions

One of the requirements for the rain clusters to be universal is that the scaling exponents, ζ_A and ζ_R , should be identical across all the oceanic basins. Our results show that the modelled rain clusters do not exhibit universality as observed in T17. First, the functional dependence ζ_A and ζ_R with the domain size Z is different across the ocean basins: the scaling exponents with domain size for AO appears to be independent of Z in contrast with the other three oceans basins. This result suggests that the scaling behaviour of model rain cluster distribution over the tropical Atlantic is different from that in the Indian and Pacific oceans. Moreover, there is no one constant value for ζ_A or ζ_R that lies within the error bounds for all three ocean basins, IO, WP and EP in Fig. 4e. The

scaling exponents in each ocean basin from the model are larger than the reported values of 1.66 ± 0.06 ($\sim 5/3$) and 1.48 ± 0.13 ($\sim 3/2$) for ζ_A and ζ_R respectively in T17, and for ζ_R reported in Quinn and Neelin (2017b) based on Special Sensor Microwave Imager data. The ζ_R values are also higher than the globally average values (1.39/1.36 simulated by model of resolution 25/50 km) reported in Quinn and Neelin (2017a). Hence, the model reproduced too few larger or heavier rain clusters and too many smaller or lighter rain clusters over the tropical oceans than observed. However, we note that the set of scaling exponents for IO curiously agrees with those reported by Peters *et al.* (2010) for the western Pacific, perhaps by coincidence.

The $E(R|a)$ for observed rain clusters of length scale of ~ 320 km and beyond were reported to scale linearly with the cluster area in T17. This was interpreted by the authors as the tendency for the larger rain clusters to grow without intensification since the average intensity within the cluster, $E(R|a)/a$, is approximately constant. On the other hand, the clusters smaller than ~ 320 km tend to grow and intensify simultaneously as $\beta \sim 4/3$ in the observations. Although β in the model generally agrees with the observed value in T17 for the smaller rain clusters, no crossover of the scaling exponent for $E(R|a)$ was seen for the larger rain clusters in the model (Fig. 5). It therefore appears that the modelled rain clusters continue to intensify as the rain clusters grow in size, but less and less effectively as $0 < (\beta-1) < 1$. This is so even for superclusters of ~ 1000 km in size ($\sim 700 \Delta A$), suggesting that the self-organisation of the large-scale precipitation in the model departs significantly from reality.

Our results also suggest that the model could over-predict the rain intensity for synoptic rain clusters. A possible consequence is that the anomalous diabatic heating by these synoptic rain clusters would reduce the static stability of the atmosphere and consequently reduce the equivalent depth of the convectively coupled equatorial waves in the model. In addition, such large-scale

release of extra latent heat would also necessitate an anomalous large-scale ascent within the rain clusters and a compensating large-scale descent outside the rain clusters. We suspect that these anomalous large-scale circulations would potentially confine further convective development to within the clusters, causing them to grow into unrealistic basin-wide continuous rain bands highlighted in Section 2. As we know that energy interacts across scales in non-linear flow dynamics, the emergence of excessive spectral power at large scales would affect the spectral power at small scales. Consequently, it is hard to expect the scaling exponents ζ_A and ζ_R to be well-captured in the model despite having excluded those erroneous basin-wide rain bands from our statistical analyses.

Although there is no common value of ζ_A or ζ_R amongst the ocean basins in the model, there is a common β and its value agrees with observations for mesoscale rain clusters. In addition, our analysis suggests that perhaps β plays a more fundamental role in the sense that it directly concerns the intensification (or dissipation) of rain clusters as they grow (or shrink). We suspect the agreement of β between the observations and the model could be because the scaling of $E(R|a)$ with a depends on a small set of dynamical processes of mesoscale deep convection that the model captures adequately as we qualitatively illustrate next.

For a rain cluster of area a , whose length scale, $\ell \equiv a^{1/2}$, is much larger than the scale height of the rain cluster, H , it is not unreasonable to view the rain cluster as a prototypical turbulent eddy in a two-dimensional turbulent fluid, where energy is transferred upscale (Kraichnan, 1967). In this turbulent framework, energy is injected within the rain cluster at the convective (small) scale as a result of the deep convection embedded within the rain clusters. The energy generated is transferred upscale to the larger scale flow within the rain cluster through the non-linearity of the turbulent flow. This view of inverse energy cascade from convective scale to the larger horizontal

flow structure in the rain cluster is consistent with the results from past investigations (Schmidt and Cotton, 1990; Moncrieff, 1992; Pandya and Durran, 1996) which show that the circulation within the mesoscale convective system (MCS; see Fig. 6b) is a gravity wave response of a latent heating profile of the MCS with a top-heavy heating profile in the vertical. For a rain cluster with cluster rain amount R [unit of volume per time], we assert that this rate of energy transferred per unit mass of air, ε , across the spatial scales is equal to the rate of latent heat released per unit mass of air within the rain cluster:

$$\varepsilon = \frac{\rho_\ell L_v r}{\bar{\rho} A H} \quad (7)$$

where ρ_ℓ and $\bar{\rho}$ are the density of liquid water and a representative air density within the cluster respectively, and L_v is the latent heat of vaporization of water. If the rain clusters are turbulent eddies within the inertial subrange of a homogeneous turbulent fluid, the kinetic energy per unit mass is characterized only by ℓ ($= a^{1/2}$) and ε :

$$u^2 \sim \varepsilon^{2/3} a^{1/3} \quad (8)$$

where u is the characteristic horizontal flow speed within the rain cluster. Using $r \propto a^\beta$ and substituting ε in Equation (8) with Equation (7), and ignoring all the constants (which we assume all variables other than u , r and a are), we have a relationship between the (horizontal) kinetic energy and the cluster area:

$$u^2 \sim a^{\frac{2}{3}(\beta-1)+\frac{1}{3}} \quad (9)$$

Alternatively, we may appeal to the archetypal MCS shown in Fig. 6 as a model for the rain cluster to obtain a scaling relation between kinetic energy and cluster area. Referring to the schematics of Fig. 6b, the upper level outflow of the MCS is maintained by the pressure difference,

Δp , between the region within the MCS (A in Fig. 6b) and the environmental air outside the rain cluster (B in Fig. 6b). Using the Bernoulli equation:

$$\frac{1}{2}u^2 \approx \frac{1}{\rho}\Delta p \quad (10)$$

Assuming that this pressure difference is primarily due to the diabatic heating of the deep convection within the rain cluster:

$$\frac{1}{\rho}\Delta p \approx c_p\Delta T \approx \varepsilon\tau \quad (11)$$

where c_p is the specific heat capacity per unit mass of the air at constant pressure; ΔT the horizontal temperature difference between A and B in Fig. 6b; τ , a characteristic time scale of the MCS. Adopting an argument put forth by Emanuel (1994), we assumed that in time τ , the deep convection within the MCS would exhaust a conditionally unstable air near the surface of thickness d , covering an area similar to (or at least proportional to) the rain cluster area:

$$\tau \approx \frac{ad}{p_c v_c} \quad (12)$$

where v_c is the characteristic horizontal air speed for the thickness d feeding into the convective area and p_c is the perimeter of the convective “patch” (see Fig. 6a). In the absence of any background wind, i.e. in a purely convective overturning case, v_c would scale as the vertical updraft, which in turn scales approximately as the square root of the convectively available potential energy, CAPE. We make two further assumptions: 1) The CAPE does not vary much over tropical oceans (Emanuel, 1994); 2) $p_c \sim \ell^K (= a^{K/2})$, for some dimension exponent K . Several observational studies (Mapes and Houze, 1993; Cahalan and Joseph 1989; Benner and Curry 1998; Peter and Neelin, 2006) reported fractal dimension for the perimeter of clouds and rain clusters, with K ranging from 1.37 to 1.5. Taking all the assumptions described above together, we obtained from Equations (10) through (12):

$$u^2 \sim a^{\beta-K/2} \quad (13)$$

Equating the exponents of a in Equations (9) and (13), we have

$$\beta = \frac{3}{2}K - 1 \quad (14)$$

Hence $\beta \geq 1$ if $K \geq 4/3$. For $\beta=4/3$ as revealed by the TRMM observations analysed in T17 and captured by the WRF model here, $K=14/9$ (~ 1.56), which is just above the range of the reported values. It is interesting also to note Peter and Neelin (2006) argued that the deep convection clusters over the tropical oceans could be a gradient percolation, and consequently $K = 4/3$, which gives $\beta = 1$ according to Equation (14).

In short, the phenomenological argument above explains why β can be greater than unity, and the value of β depends on the (fractal) dimension of the perimeter of the organised deep convection within the rain cluster.

6. Conclusion

The scaling exponents of the area and total rain amount for tropical oceanic rain clusters in the predominantly deep convective regions from a numerical weather model were obtained. The model oceanic clusters did not exhibit the universality reported in T17 for observed rain clusters: the scaling exponents ζ_A and ζ_R do not agree across the ocean basins unlike what is observed. In addition, the estimated values of both ζ_A and ζ_R from all the ocean basins were larger than their corresponding observed values reported in T17. The model also produced unrealistic basin-wide clusters within the ITCZs in all the ocean basins, which were excluded from our estimates of scaling exponents.

The scaling of the model conditional mean rainfall, $E(R|a)$, with the rain cluster area a was better replicated. A robust constant value was found for the scaling exponent β across all the ocean

basins in the model and its value 1.36 ± 0.05 is close to the observed β of about $4/3$ for mesoscale clusters of sizes about 36 km to 320 km. Hence, the model was able to reproduce the correct increase in the average rain intensity with increasing rain cluster area. We interpret this as an indication that the model has captured the fundamental and universal nature of mesoscale convective flow dynamics, as illustrated conceptually by a dimensional argument based on a simple model.

Notwithstanding the above success, the model failed to reproduce the crossover in the scaling of $E(R|a)$ as cluster size increases beyond ~ 320 km as seen in T17, where the average rain intensity of the synoptic scale rain clusters is observed to be independent of the cluster area (i.e. $\beta \sim 1$). In the model, the intensification of rain with cluster size continues with the same $\beta \sim 4/3$ for the synoptic rain clusters. We think that this may be the reason why unrealistic basin-wide rain bands form in the model leading indirectly to the model's scaling exponents ζ_A and ζ_R deviating from reality.

The modelling community has advanced rapidly in recent years, partly in association with the activities in the sixth generation of the Climate Model Intercomparison Projection (CMIP6). For example, many models in the high-resolution Model Intercomparison Projection (HiehResMIP, Harrsma et al. 2016) have horizontal resolution of the order 20-50 km, which is comparable to that in the WRF applied in this study. Whereas these high-resolution models still apply convection parameterization as in our WRF model, the simulated rainfall as the sum of that explicitly resolved and that from the parameterization scheme is also similar. Our theoretical arguments have suggested that the scaling exponent $\beta = 4/3$ (equation 5) depended only on a few fundamental features of known mesoscale convection system, hence we expect most models to reproduce this exponent. It would be important to see whether these models also produce super

(domain-spanning) clusters as what we observed with the present model, and whether they are able to reproduce the observed scaling transition to the $\beta = 1$ scaling (i.e., simple merging process). If there are a variety of different scaling behaviour across these models, further investigations could be followed up to understand how much of the differences in the modelled scaling properties of the rain clusters may be attributed to the model details, for example the convection parameterisation used.

Advances in climate modelling include the global cloud-resolving models such as those applied in the Dynamics of the Atmospheric general circulation Modeled On Non-hydrostatic Domains (DYAMOND, Stevens et al. 2019, see also Satoh et al. 2019). As all the cloud microphysical processes are modelled explicitly, the scaling behaviours of the rain clusters from these models may be used to assess the impact of cumulus parameterisation on the scaling behaviour of the tropical rain clusters. Our suggested scaling exponents for the tropical rain clusters may also be useful in assessing idealized Radiative-Convective Equilibrium (RCE) models, such as those model intercomparison project in the RCE-MIP (Wing et al. 2017). In the RCE-MIP, cloud cluster aggregation was identified as a feature to be assessed using metrics including organisation index, subsidence fraction and autocorrelation length (Wing et al. 2017). We believe the rain cluster scaling exponents of A and R can be considered as another set of metrics to evaluate cloud clustering and aggregation in these RCE models.

Although extreme precipitation is not the focus in this study, our findings have implications for the recent studies on the relationship between precipitation extremes and convective organisation / aggregation (e.g., Semie and Bony 2020). One of the debates in these studies is whether precipitation extreme increases with convective organisation with the definition of extreme varying from instantaneous to short timescale (e.g., daily), and spatially considering area-

specific extreme or only that within deep convection (see review in Pendergrass 2020). So far the result of $\beta \sim 4/3$ from both observations and our current model analysis suggests that the extreme part of the within-cluster rainfall *intensity* ($R/A \sim A^{1/3}$) likely would increase with the degree of organisation, at least for those mesoscale convective clusters or smaller. However, a more explicit comparison between our identified organised clusters with other measures of organisation is needed. On the other hand, the scale regime of $E(R|a)$ changes to $\beta = 1$, at least for the larger observed rain clusters beyond length scale of ~ 300 km (T17). If the cluster rain within this regime grows in size mainly through agglomeration of smaller rain clusters, the domain-averaged extreme precipitation intensity ($R/A \sim \text{const}$) might very well be independent of the fractional area of rain. However we cautioned that the above speculations of what our analysis of the scaling exponent of first order moment of the (conditional) rain cluster distribution ($E(R|a)$) would reveal about the relation between extreme rainfall and the organisation of a rain cluster had implicitly assumed that the higher order moments of the rain cluster rainfall distributions were independent, or at the very least, not a strong function of the cluster area. Further investigations would be needed to determine whether these assumptions are valid.

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Table 1 The estimated the scaling exponents. Bolded values in the first two rows are estimates for which the regression p-values are less than 0.05. β is estimate of exponent b in Equation (5). The last row shows the estimates of β using the scaling relation Equation (6) in the main text.

	IO	WP	EP	AO
ζ_A	2.12 ± 0.10	2.48 ± 0.09	2.37 ± 0.16	2.12 ± 0.08
ζ_R	1.89 ± 0.07	2.21 ± 0.12	2.38 ± 0.17	1.97 ± 0.21
β	1.31 ± 0.08	1.28 ± 0.04	1.33 ± 0.07	1.42 ± 0.54
$\hat{\beta}$	1.26 ± 0.18	1.22 ± 0.18	1.00 ± 0.24	1.16 ± 0.34

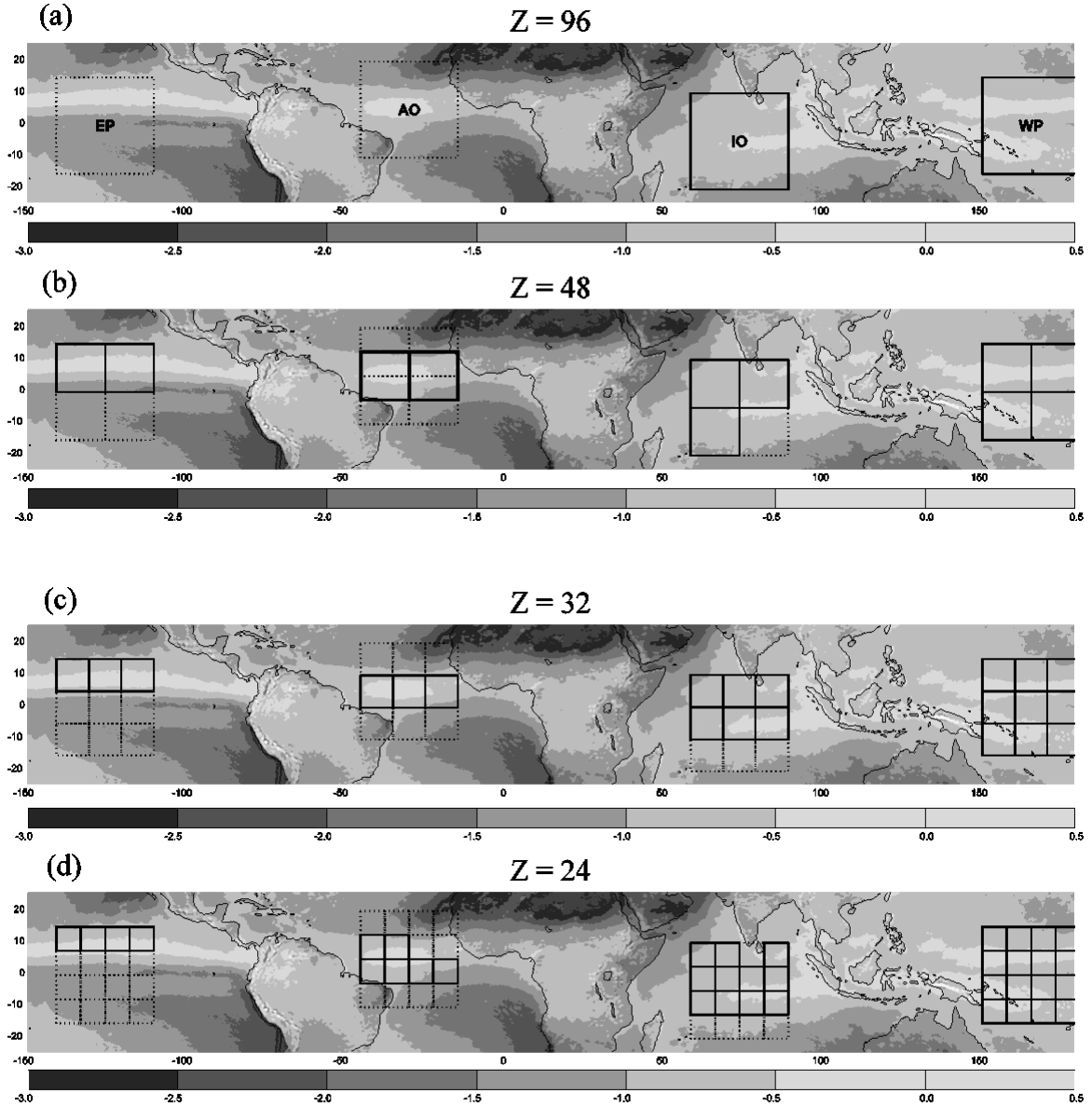


Figure 1 Selected domains for different Z together with the mean model rain intensity. Boxes with solid (dotted) edges are domains that passed (failed) the selection criteria. The contours are the mean model rain intensity (mm/hr) from 1988 – 2015 in logarithmic scale. The two boxes with thicker borders in the AO domain in (b) are two additional $Z = 48$ domains added for analysis (see main text for details).

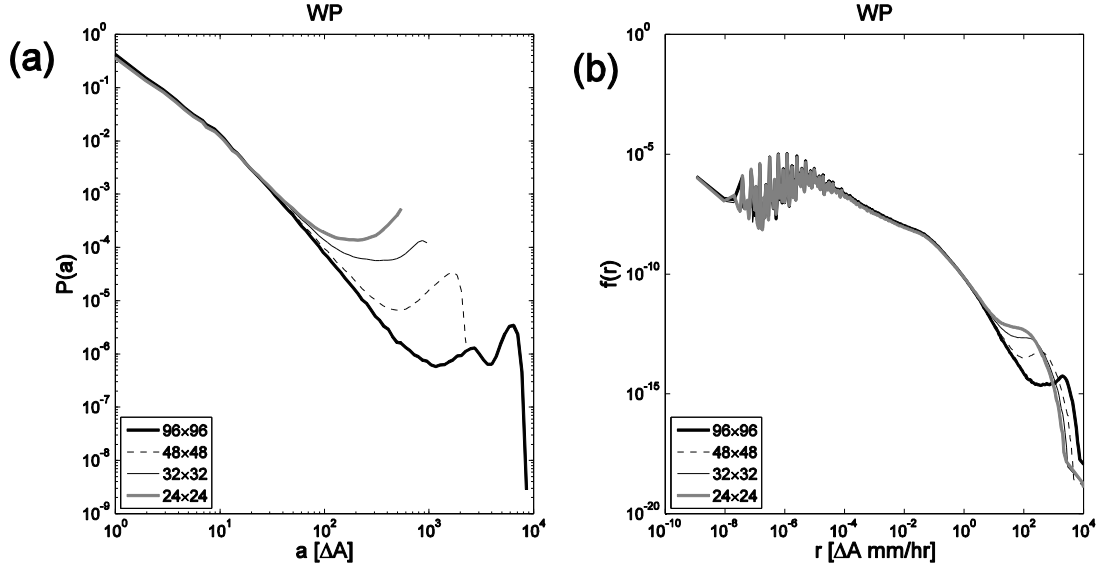


Figure 2 Double logarithmic plots of the mean of the ensemble probability distribution of rain cluster area A (a) and total cluster rain rate R (b) over WP of Fig. 1. A and R are measured in units of ΔA and ΔA mm/hr respectively, where ΔA is the (assumed constant) representative area of an evaluation grid point in the model output. The domain size $Z \times Z$ is specified in the legend.

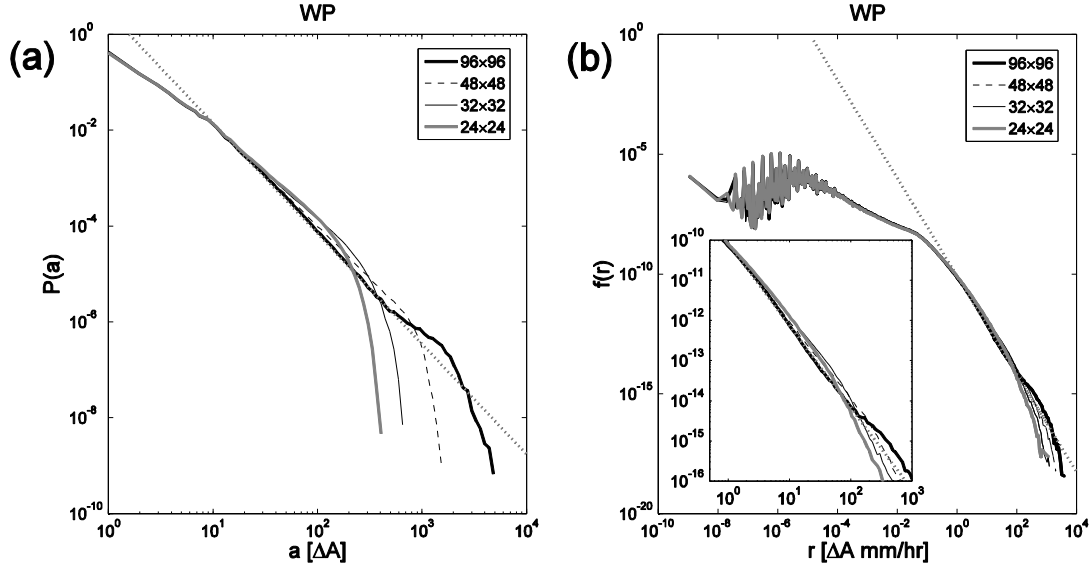


Figure 3 Same as Figure 2 but with the east-west and north-south spanning clusters excluded when computing the statistics (see the main text for details). The insert at 3(b) is the magnified view that emphasises the dependence of the scaling exponent on the domain size. The grey dotted lines in all the plots are reference power law with their respective scale exponents, ζ_s , estimated for the $Z = 96$ domain for WP (see the main text). These reference lines are drawn as a guidance as to where the simple scaling regime are approximately assumed in this study.

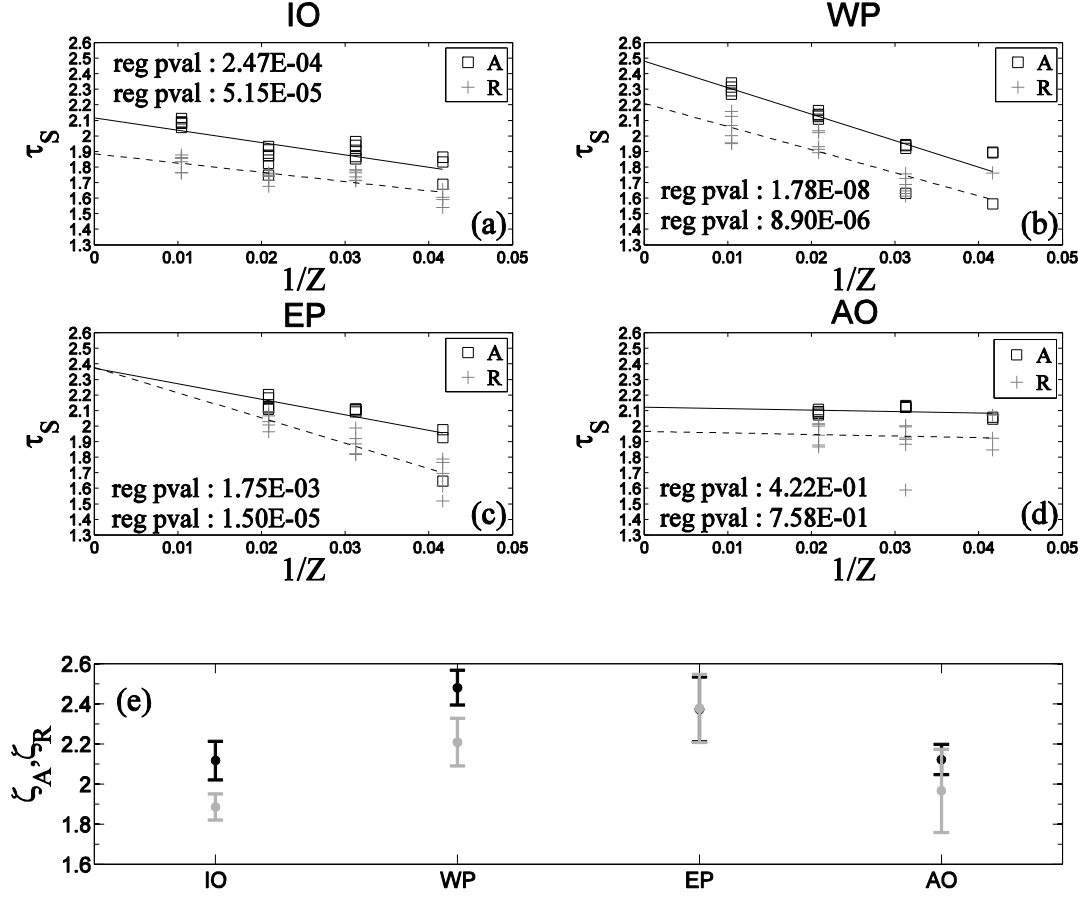


Figure 4 (a) – (d) Robust iterative least-square linear regression with Huber weights of scaling exponents versus $1/Z$ for the different focus regions for rain cluster size A , (black open squares) and total cluster rain rate R (grey crosses). Each data point in the plots is the ensemble-averaged scaling exponent, $\tau_S(Z, S_0)$, S representing A or R . (e) Estimate for ζ_A (black) and ζ_R (grey) for individual focus regions. These point estimates are the regression intercepts of (a) – (d). The error bars represent the limits at 95% confidence level of the estimates.

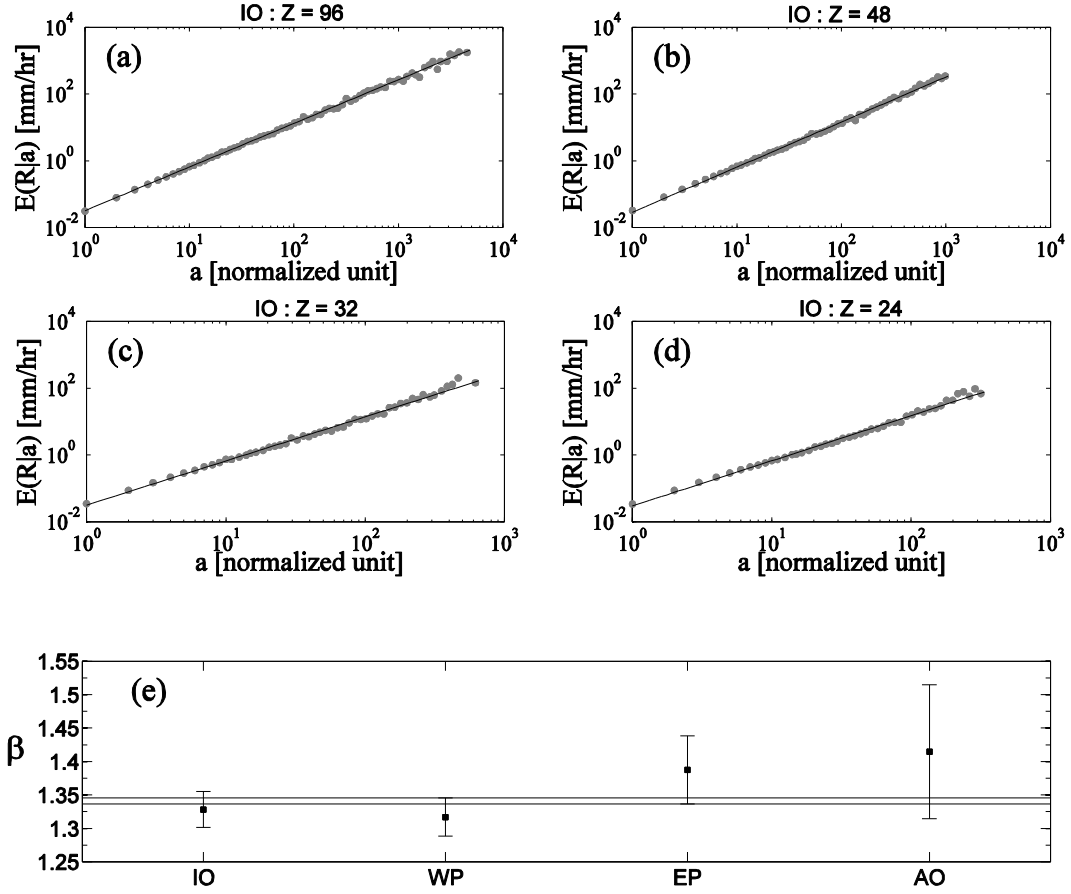


Figure 5 (a) – (d) The conditional average of cluster total rain rate with different cluster area for the various domain size over IO. The solid line shows the linear regression. (e) Estimate β for the scaling exponents of individual focus regions. The horizontal lines show the range of values where the separate estimates for all focus regions overlap. The error bars represent the limits at 95% confidence level of the estimates.

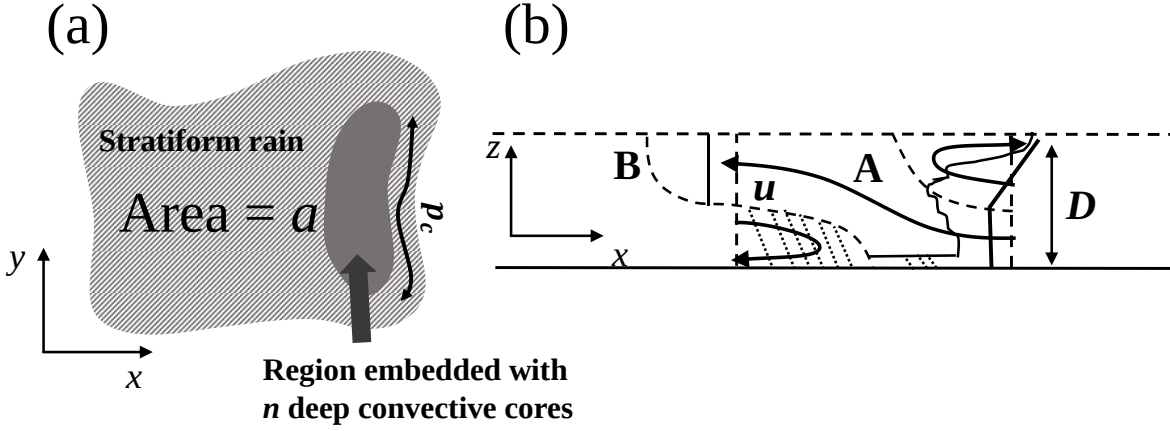


Figure 6 (a) Idealisation of a top view of a MCS divided into convective (dark grey) and stratiform regions (hatched). In the discussion in the main text, it is assumed that the convective region has a half-perimeter, p_c , and is embedded with n convective centres with strong updrafts of length scale D . (b) Schematic diagram showing the airflow relative to a two-dimensional, steady state mesoscale convective system in a large-scale environment of given wind shear. The environmental air entering the updraft is potentially unstable, and there is a pressure and temperature decrease across the system at the upper level going from A to B. The streamlines are those required by conservation of mass, momentum, entropy, and vorticity. Adopted from Houze (2004).

Appendix A: Differences in the analysis method from T17

The following are the major similarities and differences in the datasets and analysis method of this study from those in T17.

The fundamental components of the scaling analysis method are the same in both sets of analysis, namely:

- a) how a rain cluster is defined (as a set of connected rainy grids). Rain in both analyses were the total precipitation;
- b) how the empirical probability distributions for A and R (as simple-scaling ansatz for a finite domain) is defined (equation 4);
- c) the hypothesis that the finite-size scaling exponent has a linear relation with the inverse of the size of the domain: $\zeta_S(z) = m_S \times \frac{1}{z} + c_S$. The thermodynamic limit of $\zeta_S(z)$ i.e. $\lim_{Z \rightarrow \infty} \zeta_S(Z) = c_S$ is the exponent sorted.

Besides the similarity in the key assumptions of the analysis, the other details in the methods are made as similar as the difference in the two data set would allow:

- a) **Partitioning of the ocean basins (Fig. 1) into domains of size Z :** We have included a figure showing the domains used in T17 (Fig. S1) that can be compared with those in this work (Fig. 1). Due to the difference in the spatial resolution (36 km for WRF and 25 km for T17) of the two products, we began with $Z = 96$ for the modelled rain product. This $Z=96$ domain covered nearly the same geographical area as the $Z = 120$ used in T17 for

each of ocean basin. Next we proceeded to divide this large domain into smaller and smaller “square” domains. Naturally due to the different divisibility of the largest Z (96 for the current work, and 120 for T17), the possible Z values than for T17 (120,60, 40, 30, 24) are different from this work (96, 48, 32, 24). What is important to note is that the differences in the Z values used between the two analysis are not really that critical; what mattered was that we had a similar range of Z values in this work when compared to the T17 in estimating the exponents. Similar range of the Z s would mean that the uncertainties in the exponent estimates were about the same as those of T17.

- b) **Identification of the regions which were rain are predominantly from deep convection:** The idea in the original analysis was to identify regions (those square domains of the various Z s) where the rain clusters were mostly due to deep convection and not shallow convection. TRMM rainfall in T17 was the total rainfall, while we had both the grid-resolved rain from the cloud microphysics scheme and the cumulus parametrisation scheme. Comparing the accepted and rejected boxes for the various Z s in the Fig. S1 with those in Fig. 1, the boxes that were accepted for further analysis for both T17 and this work were largely similar in terms of their geographical locations. The only major difference in this work was that the method we used resulted in the rejection of all $Z=96$ and $Z=48$ domains, while T17 have “valid” domains for $Z=120$, 60 and 40 for AO. As we wish to have as close a range of Z values for the linear regression for the exponents (see above), we included two additional $Z=48$ domains (Fig. 1b) which passed our test.

- c) **Spanning clusters in modelled rainfall:** The discarding of the spanning clusters in the analyses were only done in the current analysis and not in T17 as there were no spanning clusters in T17. This difference was noted and discussed in the manuscript. We believed the existence of spanning clusters in model but not in observations deserved further investigation. In terms of our analysis, the removal of the spanning clusters was a necessity as we were mainly concern with the clusters that have size smaller than the domain.
- d) **Empirical fitting of the probability distributions:** Both T17 and current analysis used the maximum likelihood method to determine the exponents from the sample distributions (Equation 4).

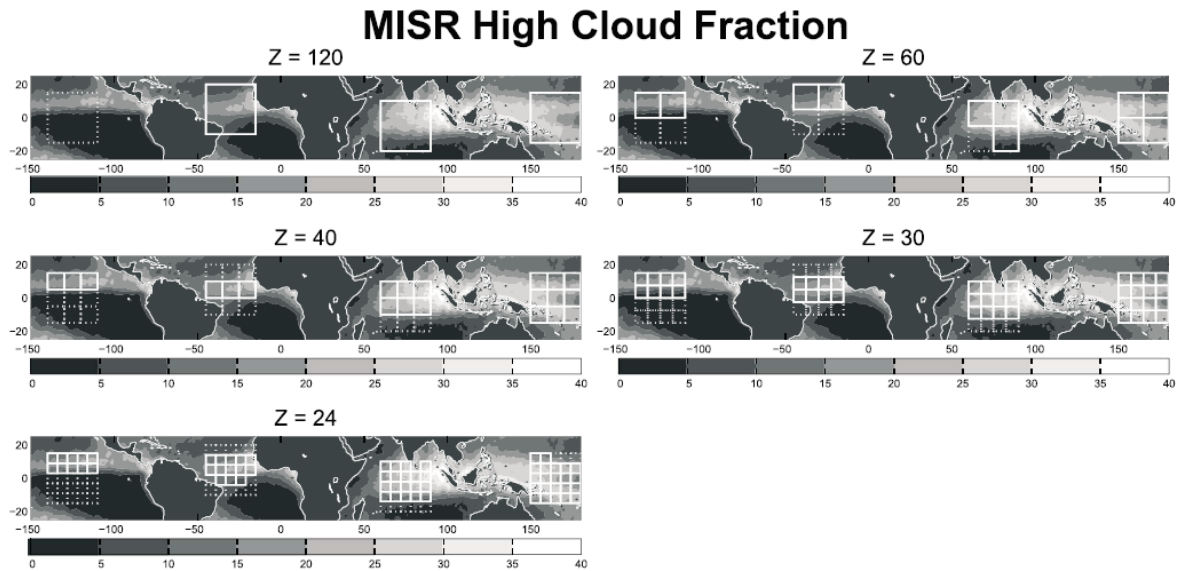


Figure S1 Domains for T17 (their Figure 2). The boxes with solid (dotted) edges are domains that passed (failed) the selection criteria imposed by T17. The contours are the satellite-derived mean annual averaged cloud fractions (reported as percentages) from 2000-2012 for clouds with cloud top height between 7 km to 15 km. Refer to T17 for details on the satellite-derived cloud climatology.

Appendix B: Comparison of the scaling exponents for R and A in T17 with those in this study

In Fig. S2 the upper panel is reproduced from Fig. 4 of T17 showing the estimates for ζ_A (black) and ζ_R (grey) for the four ocean basins estimated from observed rain clusters. The lower panel is Fig. 4e from this study with the same set of estimated scaling exponents. The estimated β values for individual oceans from this study are in Table 1 in the main text, while in T17, an estimate of β valid for all ocean basins is 1.33 ± 0.03 .

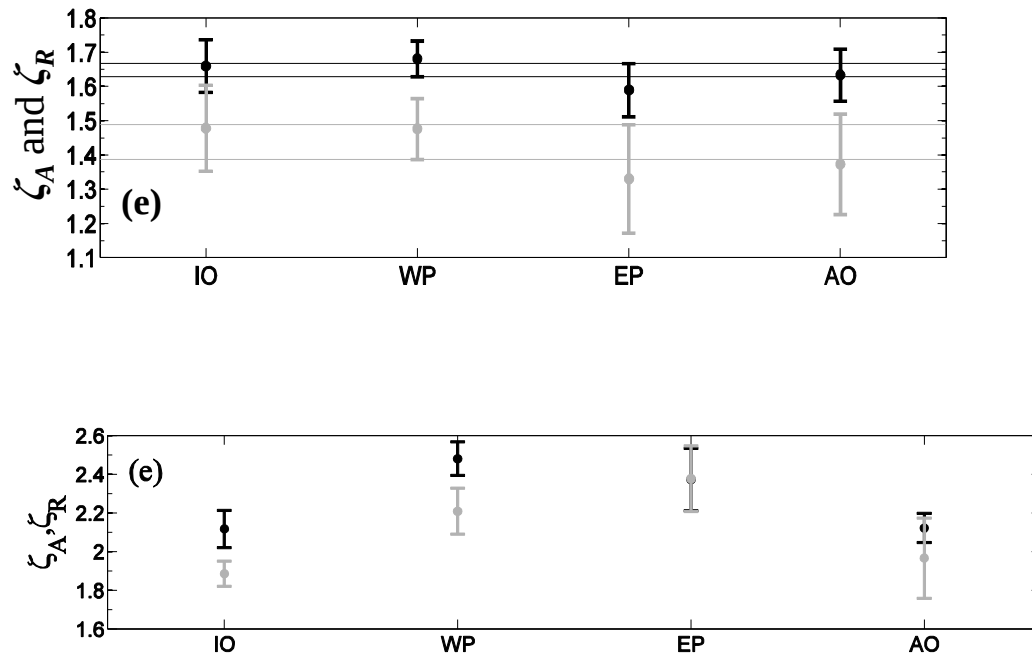


Figure S2 Comparison of the scaling exponents for R and A over the four ocean basins (IO, WP, EP and AO) in T17 (upper panel) with the corresponding values in this study (lower panel).