

Multiscale study of enhancing the fracture properties of interfacial transition zone: insights from molecular dynamics and finite element simulations

Benzhi Min^a, Xi Chen^b, Ke Li^c, Zhenqing Wang^{a,*}

^a*College of Aerospace and Civil Engineering, Harbin Engineering University, Harbin, 150001, China*

^b*Nanyang Technological University, School of Materials Science and Engineering, Singapore, 639798, Republic of Singapore*

^c*Institute of Materials Research and Engineering (IMRE), Agency for Science, Technology and Research (A*STAR), 2 Fusionopolis Way, Innovis #08-03, Singapore, 138634, Republic of Singapore*

Abstract

Cementitious composites are widely used in architecture and construction field, but usually show quasi-brittle failure at macroscale under tensile or bending loads. In contrast, the calcium silicate hydrates (C-S-H) exhibits noticeable ductile response at nanoscale. In this article, we focus on the interfacial transition zone between cement paste and aggregate, which consists of the C-S-H/quartz and the calcium hydroxide (CH)/quartz interface structures. To comprehend how a nanoscale design might improve concrete's macro mechanical qualities, molecular dynamics and finite element simulations are performed at the nanoscale and macroscale, respectively. The elastic properties, modulus, fracture toughness and critical energy release rate of C-S-H/CH/graphene oxide (GO)/quartz composites are calculated using the molecular dynamics method at nanoscale. These parameters then are used in macro-simulation and calculating mechanical properties of macro concrete structures. The incorporation of GO sheets into the interface results in a 38.40% to 58.06% increase in the fracture toughness of interfacial transition zone (ITZ) systems and an 80% and 9.81% improvement in the tensile strength and tensile modulus of the concrete model, respectively. This fundamental insight into nanoscale interfaces notably allows for more accurate predictions of macroscopic

*correspondingauthor

Email address: wangzhenqing@hrbeu.edu.cn (Zhenqing Wang)

mechanical behavior, paving the way for innovative and enhanced cement-based materials in the future.

Keywords: Calcium silicate hydrate, Multiscale modeling, Interfacial transition zone, Fracture toughness

1. Introduction

Concrete is consumed far more than any other construction material in the world [1], following water. The production of cement clinker consumes large amounts of energy and emit CO_2 , with most of the emissions occurring during the calcinations of limestone, which involves the conversion of CaCO_3 to CaO . By 2050, there will be a 4682 Mt global demand for commercial concrete, and 2543 Mt of CO_2 will be emitted during the corresponding production process [2]. Reducing CO_2 emissions will be possible, by using a mechanism-based approach at the material community to improve understanding the mechanisms that underpin cement manufacture, concrete curing, and durability [3]. Concrete is well known for its low tensile strength, low durability, quasi-brittle damage, poor deformation performance and multiple cracking behavior [4, 5, 6]. At the microscopic level, it is essential to comprehend how the good ductile damage behavior of C-S-H can lead to quasi-brittle damage behavior of macroscopic concrete. This microscopic understanding will help us to develop tougher and more durable concrete materials at the microscopic level.

Concrete is a multi-component, multi-phase and multi-scale composite material [7]. The structural integrity and load-bearing capacity are typically affected by cracks in concrete, substantially jeopardizing the safety, usability, and durability [8]. There has been lots of research on strengthening the toughness of concrete throughout the past few decades [9, 10], various fibers and nano additives have been reported as efficient concrete modifying agents. Concrete's tensile strength can be increased by steel fibers and polypropylene fibers by 47% and 22%, respectively. [11, 12, 13]. Short carbon, glass and steel fibers with different volume contents significantly increased the first crack stress, fracture energy and toughness [14, 15, 16], decreased the crack width and changed the shape of the crack path from linear pattern to curved form [17]. Fiber bridging, fiber pullout, and fiber fracture are the three basic reinforcement mechanisms of fiber reinforced concrete, which significantly affect the flexural and fracture properties of concrete by bridging the cracks and inhibiting propagation [18]. However, the addition of fiber will lead to a decrease in the mechanical properties if the fiber deforma-

tion are incompatible with matrix, and ITZ in the concrete is not enhanced [19]. Nano additives that can improve the microstructure and mechanical properties of ITZ therefore are highly favored by researchers [20, 21, 22]. Via whisker pull-out, crack deflection, whisker bridging, and whisker fracture, micro-size CaCO_3 whiskers effectively inhibited and delayed the generation, extension and coalescence of microcracks [23, 24]. Due to the improved bond strength produced by the incorporation of silica fume, adding more silica fume ($> 20\%$) contributed better to improving the fracture resistance and flexural strength of concrete than steel fiber [25]. ITZ's porosity was significantly reduced by adding GO, which also enhanced the structural morphology of the hydration products, increased the homogenization of the microstructure, and thus increased the micro fracture toughness of ITZ by 24.9% [26, 27]. Carbon nanotubes [28, 29, 30, 31] and nanoscale cellulose filaments [32] can be well dispersed and embedded in the cement hydration products, this mesh-like distribution provides good bonding ability by bridging the pores and decreasing the pore size. The filling effect of nano silica can lengthen the C-S-H gels' chains in ITZ, making the structure denser and optimizing the enhancement of mortar's fracture qualities [33, 34]. The synergistic mechanism of suppressing cracks at different scales brought by the addition of nanomaterials results in higher strength and significant fracture toughness of the cement-based composites [35]. It is clear that ITZ has the most important impact on the toughening of concrete. Understanding the interaction between additives and concrete is more difficult due to the load transmission through adhesion, cementitious material damage, as well as the plastic deformation [36]. Understanding and predicting concrete properties by modeling and simulation methods has become a pursuit of many researchers. In recent years, a variety of concrete fracture models have been developed at different scales [37, 38, 39, 40, 41], however, to simplify calculation, the models are usually applicable to a single scale (e.g. mesoscale), or simplified assumptions are made for constitutive relation at the element level. Existing multiscale models [42, 43, 44, 45] are rarely allowed to take the effects of various nanoadditives on the mechanical properties of concrete into consideration, especially fracture properties at the molecular level. Therefore, a multiscale model that allows the consideration of different types of nanoadditives, and focuses on the effect of ITZ on the overall mechanical and fracture properties of concrete, is necessary to help us better understand the effect of micro-component design on concrete properties, with the aim of reducing concrete consumption or extending the service life of concrete buildings.

In this article, we tried to construct a multiscale model for cementitious composites by molecular dynamics (MD) and finite element method (FEM). The inter-

70 action of the C-S-H/GO/quartz and CH/GO/quartz interface systems were studied
 71 using the molecular dynamics method, the radial distribution function (RDF), hy-
 72 drogen bonds, fracture toughness and energy release rate were analyzed to charac-
 73 terize the fracture behavior of different phase at nanoscale. The MD simulations
 74 help us comprehend the mechanism of GO toughening ITZ and provide a series
 75 of parameters for fracture properties. These key parameters allow us to construct
 76 a finite element model to predict how the interaction between the cement ma-
 77 trix and aggregates affects the concrete's overall fracture properties. The models
 78 utilized in this study provide a detailed understanding of how nanoscale design
 79 strategies have the potential to augment the macroscopic mechanical properties of
 80 concrete materials. This lays the groundwork for the advancement and refinement
 81 of cement-based materials in the future.

82 2. Materials and methods

83 In this study, we focused on the interfacial transition zone (ITZ) between ce-
 84 ment paste and aggregate, the weakest part of concrete. The C-S-H/quartz and
 85 CH/quartz interface structures are chosen as the two fundamental structures of
 86 ITZ, since C-S-H and CH are the two main products in ITZ. To comprehend how
 87 a nanoscale design might improve concrete's macro mechanical qualities, molec-
 88 ular dynamics models and finite element models were developed at the nanoscale
 89 and millimeter scale, respectively.

90 2.1. Molecular dynamics model

91 2.1.1. Model construction

92 Fig. 1 shows the main parts of the interfacial transition zone structures: amor-
 93 phous C-S-H layers, CH, GO sheets, and quartz. The typical structure of tobermorite-
 94 11 Å (Hamid) [46] ($a/2 = 5.58 \text{ Å}$, $b = 7.39 \text{ Å}$, $c/2 = 11.389 \text{ Å}$) was used to cre-
 95 ate the atomic structure of the C-S-H crystal. Previous studies have demonstrated
 96 that under various mix proportions and curing processes, the average Ca/Si ra-
 97 tio of C-S-H gel in ordinary cement paste ranges from 1.2 to 2.3 [47] with a
 98 mean of 1.75, which is consistent with the nuclear magnetic resonance (NMR)
 99 results [48]. In order to keep the C/S ratio around 1.7, large numbers of SiO_2
 100 groups were randomly removed from silicate tetrahedron chains. The final C-
 101 S-H structure contains monomers, dimers, pentamers and even octamers with
 102 $Q^0 = 10\%$, $Q^1 = 68\%$ and $Q^2 = 22\%$ respectively. Then the Grand Canonical
 103 Monte Carlo (GCMC) simulation was carried out to adsorb water molecules.
 104 After the reaction between water and Ca SiO_4 groups, we obtained the final

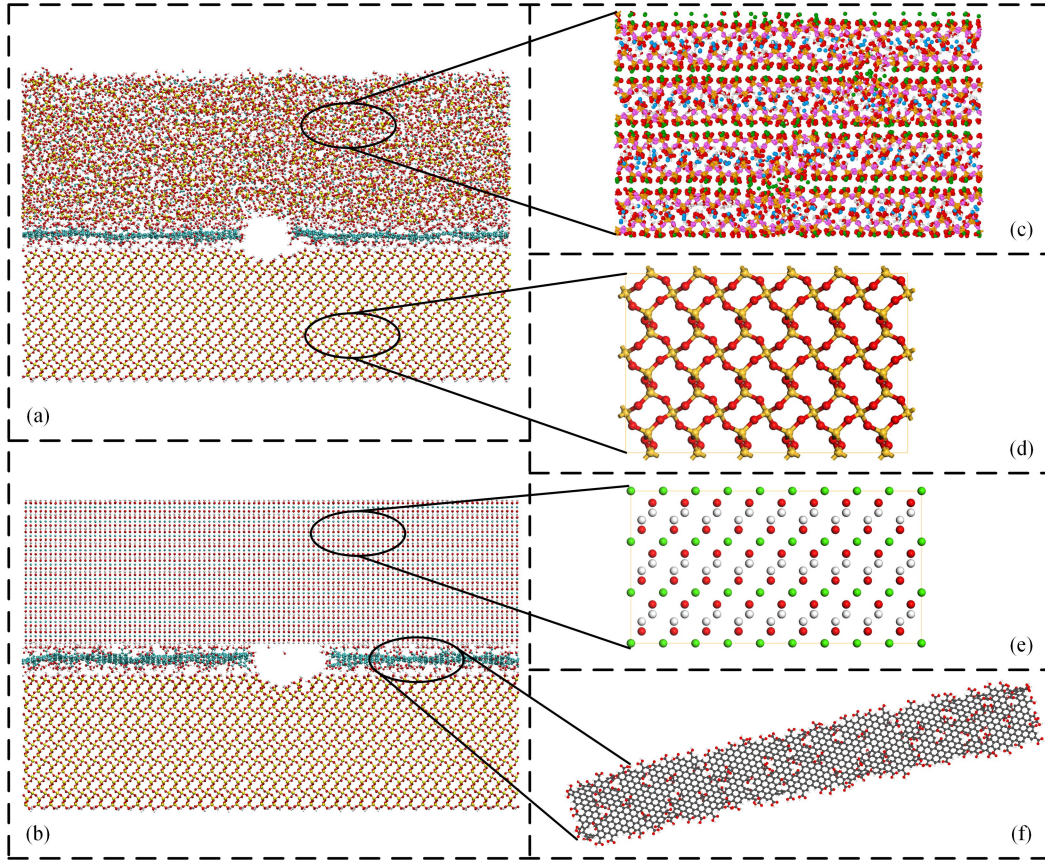


Figure 1: Construction of molecular models: (a) The interface between C-S-H and quartz. (b) The interface between CH and quartz. (c) C-S-H chains with C/S ratio of 1.7. (d) The unit cell of quartz. (e) CH unit cell. (f) GO sheet embedded in the interface. The green, blue, yellow, red, gray and white balls represent interlayer calcium, intralayer calcium, silicon, oxygen, carbon and hydrogen, respectively.

105 amorphous C-S-H structure, as shown in Fig. 1 (c). Please refer to our pre-
 106 vious work [49] for more details about the minimizing, GCMC and reaction
 107 procedure. Crystals enriched in $\text{Ca}(\text{OH})_2$ have also frequently been detected in
 108 the ITZ of cementitious composites in addition to C-S-H [50, 51, 52]. There-
 109 fore, both the C-S-H and CH components in the ITZ must be taken into ac-
 110 count if we are to comprehend the mechanical characteristics of the ITZ. The
 111 C-S-H/quartz and CH/quartz structures are the two interfacial structures we gen-
 112 erated after simplifying the aggregate portion to quartz crystals, as illustrated in
 113 Fig. 1 (a) and (b). Fig. 1 (e) is the crystal structure of CH [53], with unit cell

lattice parameters $a = b = 3.5862 \text{ \AA}$, $c = 4.8801 \text{ \AA}$, $\alpha = \beta = 90^\circ$, $\gamma = 120^\circ$. As shown in Fig. 1 (d), unit cell of α -quartz ($a = b = 4.913 \text{ \AA}$, $c = 5.4052 \text{ \AA}$, $\alpha = \beta = 90^\circ$, $\gamma = 120^\circ$) is used as the quartz phase. Graphene oxide (GO) sheets were embedded in the C-S-H or CH quartz interfaces to improve the fracture toughness of the fragile ITZ phase. Fig. 1 (f) shows the schematic model of GO atomic structure, expanded from the graphene unit cell with lattice parameters $a = 2.46 \text{ \AA}$, $b = 4.26 \text{ \AA}$, $c = 3.4 \text{ \AA}$ and $\alpha = \beta = \gamma = 90^\circ$. Since the oxygen atoms in -COOH functional groups are 20% of the number of carbon atoms in GO, corresponding carbon atoms should be removed in order to produce the desired number of -COOH groups. The functional groups were then randomly distributed at the edge and inside of graphene skeleton. Last, the optimized GO structures were inserted into the gap ($10 \text{ \AA}$) of the C-S-H/quartz and CH/quartz interfaces to enhance the mechanical properties of the interface phase.

2.1.2. Force field and loading process

In this research, the Large-scale Atomic/Molecular Massively Parallel Simulator (LAMMPS) [54] was used for all MD simulation operations. The amorphous C-S-H phase which is congruent with experimental evidence that results from the reaction of water molecules with Ca^{2+} ions or Silica tetrahedron is described, using the reactive force field (ReaxFF) [55]. Using the ReaxFF, water molecules will dissociate in the simulation to produce the Si-OH and Ca-OH groups. A general force field for clay phases (ClayFF) [56, 57] was employed to calculate the atomic interactions in C-S-H, CH and quartz crystal during the tensile procedure. ClayFF, a parameterized force field, is used to characterize systems with simple oxides, hydroxides, and oxyhydroxides. Only the bonds in hydroxyls are explained using the bond stretch and bond angle bend expressions; all metal-oxygen interactions are represented using Lennard-Jones and Coulomb potential. As a result, it works well with other complicated structures. For a variety of silica mineral systems, the usefulness of this force field in forecasting the structure and binding strength has been demonstrated [58, 59, 60]. The atomic potential in the GO phase was described using the consistent-valence force field (CVFF) [61], which has been demonstrated being effective for organic substances [62]. In this work, standard Lennard-Jones (12-6) potential terms between CVFF and ClayFF phases were mixed using geometric (Lorentz-Berthelot) combining rules [63].

Throughout all the MD tensile simulations, the interface models were subjected to uniaxial tensile displacement with a strain increment of 10^{-6} per femtosecond, and the time step was set to 0.1 femtoseconds. Before applying tensile loads, the entire interface system needs to be run for 1 nanosecond at 300 K and

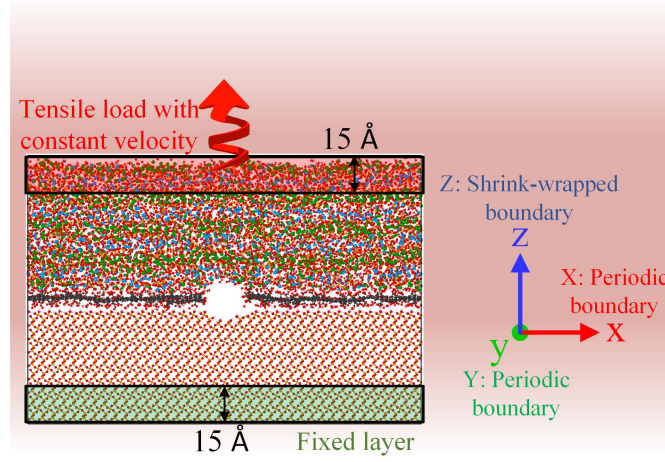


Figure 2: The loading and boundary conditions of MD system.

0 atm under an isothermal–isobaric ensemble (constant temperature and constant pressure ensemble, NPT), to establish a fully balanced interfacial structure. As the tensile process progressed with $T = 300$ K, the ensemble of interface system was then switched to a canonical ensemble (constant volume and constant temperature ensemble, NVT). As shown in Fig. 2, by setting the atom's velocity to zero, a layer of $15 \text{ \AA}$ was fixed at the bottom of quartz atoms. On the contrary, a layer of $15 \text{ \AA}$ on top of the C-S-H or CH phase were provided with a constant velocity in the z direction (perpendicular to the interface) as the tensile load. Periodic boundary conditions (PBC) were applied to X and Y axes. If the Z-axis direction is also set to PBC, the atoms at the top and bottom of the box will interact and form a new interface, which is not desired result. Therefore, we set the Z-axis direction to shrink-wrapped boundary condition, which allows the boundary of the simulation box to change synchronously with the maximum or minimum coordinates of the atoms and cuts off the interactions of the atoms across the box.

2.2. Finite element model

2.2.1. Model construction

At the macroscale, a model that incorporates the different phases of cement paste, aggregates, and ITZ, as well as the distribution of C-S-H and CH is need. Fig. 3 shows the distribution of diameters of aggregates in an ideal concrete model. The 2D Walraven-Fuller curve was chosen for the aggregates gradation

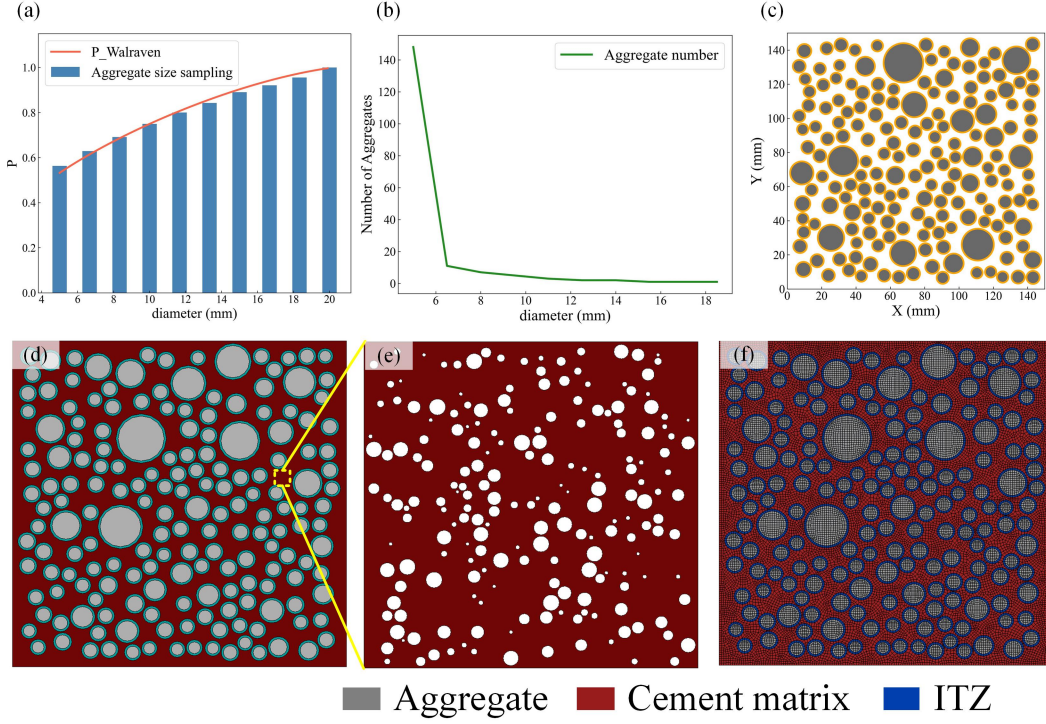


Figure 3: Distribution of the diameters of aggregates in concrete finite element model and 2D Finite element model of concrete with aggregates, cement paste and ITZ. (a) The 2D Walraven-Fuller curve of aggregates gradation. (b) Numbers of aggregates at different diameters. (c) Location and size of aggregates in a $150\text{mm} \times 150\text{mm}$ square concrete sample. The gray circles represent aggregates. (d) Finite element model of concrete sample, in which the annulus around the aggregates represent the ITZ. (e) Representative volume element (RVE) of cement matrix with pores. (f) Meshed concrete sample with different materials assigned. In (f), the gray, dark red and dark blue elements represent material of aggregates, cement matrix and ITZ, respectively.

171 of the FEM model, as can be seen from Fig. 3 (a). Walraven-Fuller curve can be
 172 calculated from the following equation,

$$P_d = 1.065 \times \left(\frac{d}{D_{max}}\right)^{0.5} - 0.053 \times \left(\frac{d}{D_{max}}\right)^{4.0} - 0.012 \times \left(\frac{d}{D_{max}}\right)^{6.0} - 0.0045 \times \left(\frac{d}{D_{max}}\right)^{8.0} - 0.0025 \times \left(\frac{d}{D_{max}}\right)^{10.0} \quad (1)$$

173 where P_d is the percentage by weight of aggregates with diameter not greater

174 than d , and D_{max} is the diameter of the largest aggregate. Here, P_d is a cumulative
175 value and the maximum value is $P_{D_{max}} = 1$.

176 The total volume fraction of aggregates to concrete was set to 40%. By sam-
177 pling from this Walraven-Fuller curve, about 200 aggregates with diameters be-
178 tween 5 and 20mm was generated. Fig. 3 (b) presents the numbers of aggregates
179 at different diameters. After obtaining diameter data of all the aggregates, we need
180 to randomly disperse the aggregates in the concrete specimen model. A python
181 script was used to automatically drop the aggregates. We partitioned the entire
182 model into grids with a spacing of 0.2mm in order to speed up and improve the
183 program's success rate when placing aggregates. When the being placed aggre-
184 gate is detected as not satisfying the minimum distance from other aggregates, it
185 will randomly move its center within the grid. It will be redelivered if the aggre-
186 gate still not match the requirements after several attempts of movement. Fig. 3
187 (c) shows the location and size of all the aggregates in a 150mm $\times$ 150mm square
188 concrete sample. In Fig. 3 (d), the finite element model was established and was
189 divided into three region: cement paste (dark red), ITZ (green annulus) and ag-
190 gregates (gray). Calcium hydroxide and C-S-H are the two main hydrate phases
191 that dominate the microstructural development of Portland cement, where C-S-H
192 is mainly deposited close to the cement particles and CH is mainly deposited close
193 to the pores. Here, we set the volume fractions of C-S-H, CH, and micropores in
194 matrix to be 77%, 8%, and 15%, respectively. Similarly, the fraction of C-S-H,
195 CH and pores in the ITZ phase were set to 57%, 13% and 30%, [52]. In Fig. 3 (e),
196 a representative volume element (RVE) model of cement matrix only was con-
197 structed to investigate the overall damage evolution of cement paste. As shown
198 in Fig. 3 (f), parameters of cement matrix, ITZ and aggregate calculateed from
199 homogenization of C-S-H, CH, Quartz, C-S-H/GO(if any)/quartz and CH/GO(if
200 any)/quartz were attributed to the corresponding region.

201 2.2.2. Constitutive response of elements

202 In this article, ABAQUS was employed to perform simulations of finite ele-
203 ment models. Cohesive elements with zero thickness were embedded in the whole
204 model in order to simulate the crack expansion along an arbitrary path in the spec-
205 imen. To match the morphological structure distribution, the cohesive elements
206 that are dispersed in different regions (ITZ, matrix, aggregate.) and materials (C-
207 S-H, CH, etc.) were automatically detected and given the relevant mechanical
208 properties. The constitutive response of the cohesive elements can be defined by
209 the traction-separation relation, as shown in Fig. 4. The key parameters, stiff-
210 ness K , peak traction stress σ^{max} and fracture energy G^C , can be obtained from

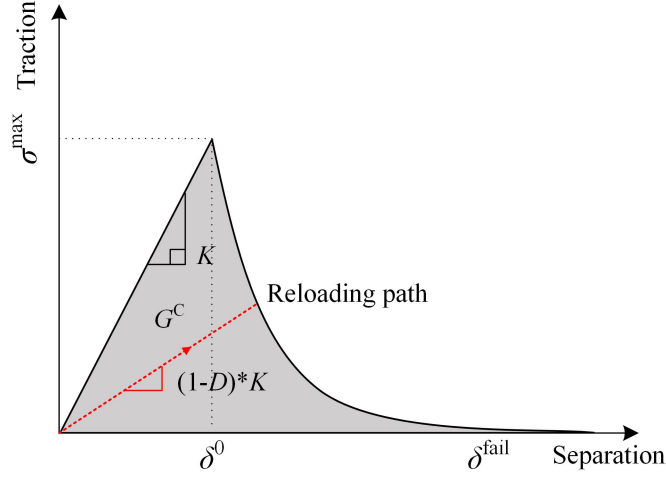


Figure 4: Traction-separation response of cohesive elements for damage evolution.

the molecular dynamics simulation results. The quadratic nominal stress criterion was used to determine whether the damage initiation of cohesive element. As shown in Eq. 2, when the sum on the left side of the equation equals to 1, the cohesive elements begin to suffer irreversible damage. Power law was used to define the fracture criterion of fracture energy. The evolution of the damage variable D is softened according to Eq. 3.

$$\left\{ \frac{\langle \sigma_n \rangle}{\sigma_n^0} \right\}^2 + \left\{ \frac{\sigma_s}{\sigma_s^0} \right\}^2 + \left\{ \frac{\sigma_t}{\sigma_t^0} \right\}^2 = 1 \quad (2)$$

$$D = \int_{\delta_0}^{\delta^f} \frac{\sigma_{eff} d\delta}{G^c - G_0} \quad (3)$$

in which $\langle \rangle$ is the Macaulay bracket, $\sigma_n, \sigma_s, \sigma_t$ are the three components of traction stress vector. The corresponding peak value of traction at the initial damage are denoted by $\sigma_n^0, \sigma_s^0, \sigma_t^0$. G_0 is the elastic energy at damage initiation. σ_{eff} and δ are the effective traction and displacement.

In this paper, uniaxial tensile simulations are performed for single-aggregate and multi-aggregate FEM models, and the same boundary conditions are applied for both. As shown in the Fig. 5, the horizontal (U1) and vertical (U2) displacement of the bottom boundary of the model are constrained to be zero. The top boundary has only the horizontal displacement constrained to zero, and a displacement load was applied in the vertical direction to simulate uniaxial tension.

227 In order to get the magnitude of external force applied to the model, a reference
 228 point was created away from the top surface and the load was applied to the ref-
 229 erence point. The force acting on the reference point during the simulation was
 230 equal to the magnitude of the applied external force.

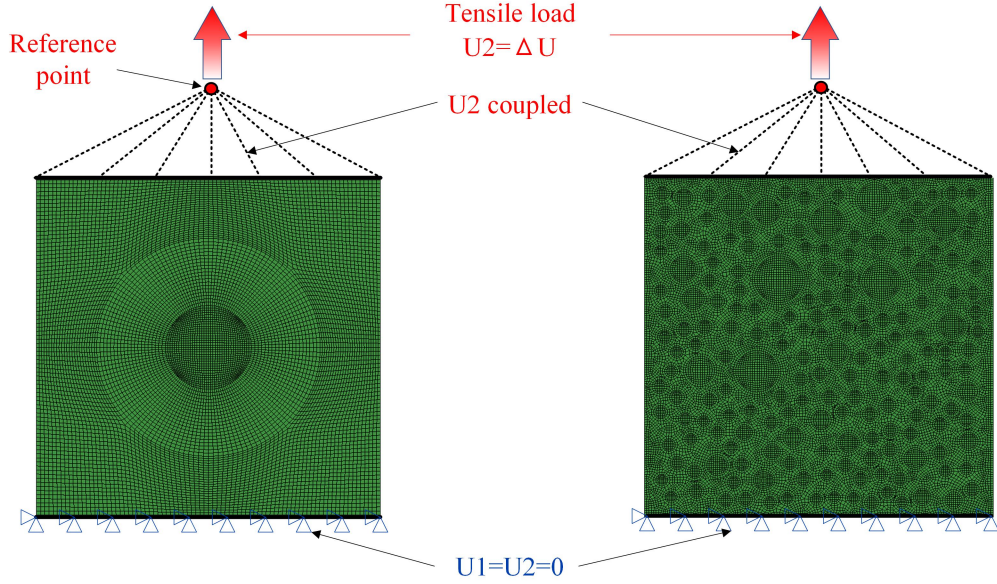


Figure 5: The loading and boundary conditions of single-aggregate and multi-aggregate FEM model.

231 3. Results and discussion

232 At the atomic level, a fracture happens when the bonds between atoms are
 233 broken along a fracture plane, generating new surfaces. The theoretical strength of
 234 the material is therefore determined by the interaction between atoms. To describe
 235 a material's capacity to resist crack growth, the energy release rate (G) and stress
 236 intensity factor (K) are typically used parameters,

$$W = \frac{1}{2} \int_0^a p(x,0) \bar{u} T dx \quad (4)$$

237 in which the W is the work done to extend the crack, the $p(x,0)$ is the crack
 238 normal stress distribution in the corresponding crack-free body. $\bar{u}$ is the total
 239 opening displacement of crack at position x and T represents the thickness of the

body. The energy release rate of the crack propagation can be expressed by the following equation,

$$G = \frac{dW}{dA} = \frac{1}{2} \int_0^a p(x, 0) \frac{d\bar{u}}{dA} T dx \quad (5)$$

where A is the area of the corresponding crack. Fig. 6 demonstrates how to determine the crack area for a given frame from the results of the MD simulation. The blue translucent bubble in Fig. 6 (a) represents the pores of crack during tension. The free volume of pores is determined by calculating real space function in the MD simulation box. It was performed by a Multifunctional Wavefunction Analyzer (Multiwfn) [64] using 1.8 times van der Waals radius as the full width at half maximum of Gaussian function. As shown in Fig. 6 (b), the crack area is determined by the projection of the free volume on the horizontal plane.

The energy release rate and the stress intensity factor are two parameters frequently used to describe the fracture characteristics of materials. For the opening mode (Mode-I), the relationship between critical energy release rate G_C and fracture toughness K_{IC} can be expressed by Eq. 6,

$$G_C = \frac{K_{IC}^2}{E'}, E' = \begin{cases} E & , plane stress \\ \frac{E}{1-\nu^2} & , plane strain \end{cases} \quad (6)$$

where E' is related to Young's modulus E and Poisson's ratio ν . Here the plane strain case is applicable to our current study.

3.1. Fracture properties of matrix and aggregate phase at nanoscale

In order to monitor the crack area, we need to create an initial crack in the atomic structure and make it the location where the crack starts. The atoms in the structure will be removed when the coordinates fall within an ellipse whose diameter of the major axis is five times the minor axis, as shown in Fig. 7 (a). To keep the system electrically neutral, the selected atoms will be deleted in the form of a group of atoms with a total charge of zero. The values of critical energy release rate are plotted against the size of initial crack in Fig. 7 (b). The size of the initial crack can affect the plastic deformation region in the structure, and to exclude this effect, structures with two different C/S ratios were used to calculate the energy release rates at different initial crack sizes. Compared with $G_C = 1.72 \pm 0.29 J/m^2$ of $C/S = 1.65$ in the literature [65] and $G_C = 2.0 J/m^2$ of $C/S = 1.0$ in [66], the critical energy release rate of two C-S-H structure with $C/S = 1.7$ and $C/S = 1.0$ are $G_C = 1.81 \pm 0.13 J/m^2$ and $G_C = 2.89 \pm 0.31 J/m^2$, respectively. The value of

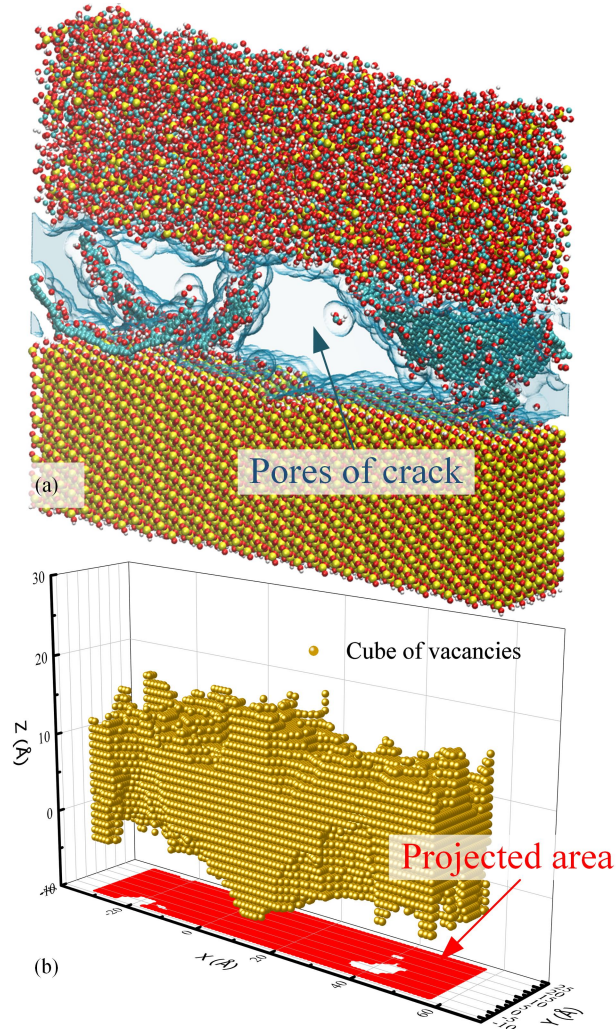


Figure 6: Estimation of the crack area in a MD simulation. (a) Schematic diagram of the pores created by the crack. (b) Spatial distribution of the cubes of the crack pores, and its projection on the horizontal plane.

the energy release rate barely changes after the length of initial crack is larger than $20\text{\AA}$. In the subsequent MD simulations, initial crack length of $30\text{\AA}$ was adopted for all phases and structures.

Fig. 8 (a) and (b) shows the atomic snapshots of quartz, CH, and C-S-H at strain = 0.1 and 0.2. The volumes of simulation boxes for quartz, CH and C-S-H are $178.50\text{\AA} \times 31.11\text{\AA} \times 98.13\text{\AA}$, $178.71\text{\AA} \times 31.52\text{\AA} \times 86.48\text{\AA}$ and $178.68\text{\AA} \times$

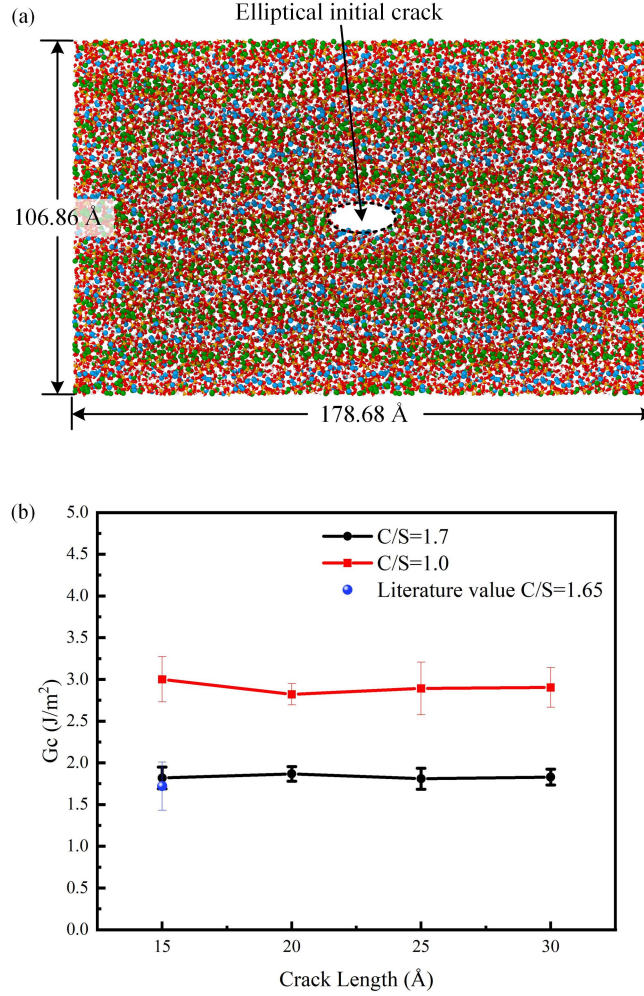


Figure 7: Effect of initial crack size on MD simulation results. (a) Illustration of the elliptical initial crack in the MD model, taking C-S-H as an example. (b) The critical energy release rate of C-S-H at different initial crack lengths.

276 $31.42\text{\AA} \times 106.86\text{\AA}$, respectively. The stress-strain curves of C-S-H, quartz and
 277 CH phases under uniaxial stretching are shown in Fig. 8 (c). The stress of quartz
 278 reaches a peak value of 42 GPa when the strain approaches 0.1, and then the crack
 279 starts to expand drastically, accompanied by a sharp drop in stress and brittle
 280 damage. Due to the effect of the initial crack, a significant number of disloca-
 281 tions are formed in the vicinity of the crack before the material is damaged, so
 282 the stress-strain curve before the stress peak is not very typical linear. At high

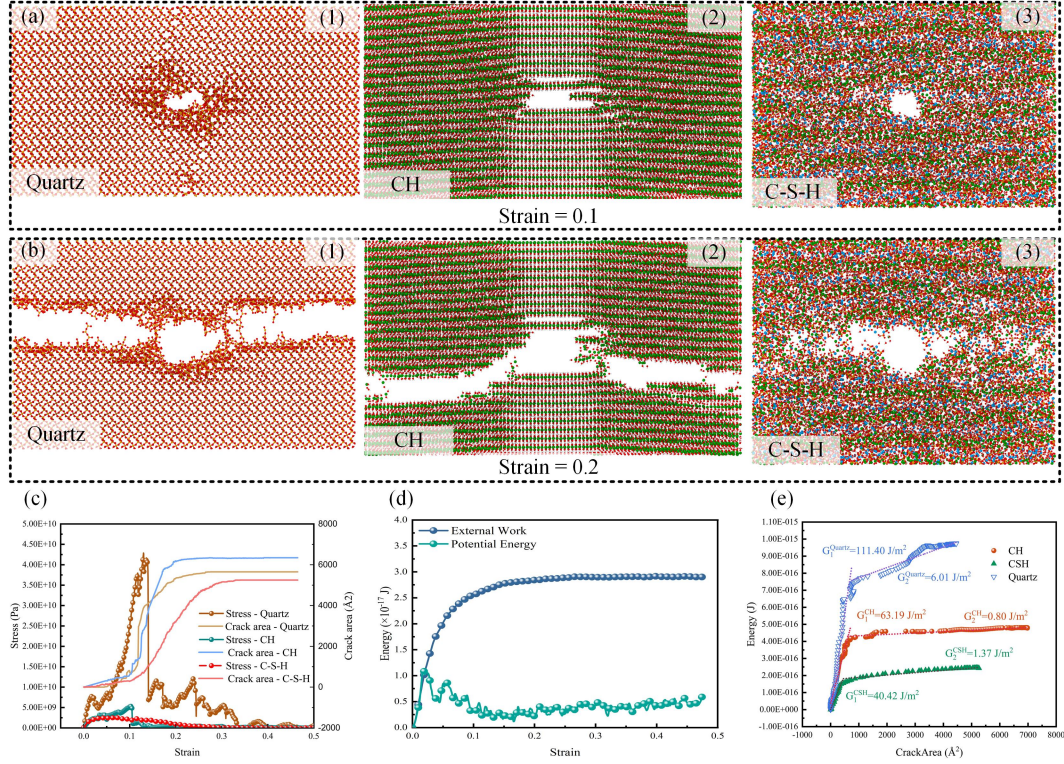


Figure 8: Atomic snapshot of quartz, CH, and C-S-H at (a) strain = 0.1 and (b) strain = 0.2. (c) Stress and crack area curves with strain. (d) Energy-strain curves. (e) Energy-crack area curve of quartz, CH and C-S-H phases.

strain, the crack quickly spreads horizontally (in the direction of the long axis of the initial crack) and penetrates through the whole cross-section of simulation box where the interatomic interaction near the crack are insufficient to sustain the stresses produced by tensile deformation. Similar to quartz, CH also exhibits apparent brittle fracture after reaching a peak tensile strength of 4.7 GPa close to a strain of 0.9. The cracks in CH grow at an angle inclined downward near the initial crack, while in most of the other regions grow along the horizontal direction (along the interlayer of Ca-OH atoms). Unlike the quartz and CH phases, C-S-H phase has more noticeable ductile damage behavior at nanoscale. The stress reaches a peak of 2.5 GPa at a strain of 0.06 and steadily declines to zero as the strain climbs to 0.3. Furthermore, the crack area versus strain curves shows that the crack extension rate of C-S-H is about twice lower than that of quartz and CH. Even at high strains, there are still some adherent atoms (mainly some short

296 silicate tetrahedron chains) playing a positive role in the connection of the crack,
 297 which contributes to the blunting of the crack tip and is one of the main factors
 298 of the C-S-H ductile response. The energy variation curve of the C-S-H phase
 299 during tensile process is depicted in Fig. 8 (d). Almost all of the external work
 300 on the system is stored as elastic mechanical potential energy during the elastic
 301 deformation stage ($strain < 0.02$), during which the crack does not propagate.
 302 Plastic deformation occurs in the system and the crack area begins to expand as
 303 the strain keeps increasing, it causes that the external work is used to generate a
 304 new surface or is dissipated by plastic deformation [67]. Fig. 8 (e) shows the work
 305 done by the average stress at both sides of the crack area in the quartz, CH and
 306 C-S-H systems. The energy increases very fast at the start of the crack expansion
 307 because the stress still maintains a high value despite its rapidly reducing. After
 308 the crack starts to expand smoothly, the energy increases slowly and steadily. By
 309 tracing the cracks, we were able to determine the fracture toughness and critical
 310 energy release rate of quartz, CH, and C-S-H phases (shown in Table 1), which
 311 are important parameters that determines the fracture response of the aggregate
 312 and cement matrix phase in the macroscale model. And we also obtained Young's
 313 modulus (E), shear modulus (G), bulk modulus (K), and Poisson's ratio (ν) in
 314 order to describe the elastic response of different phases' materials.

315 After performing deformations on the MD model, the elastic stiffness coeffi-
 316 cients C_{ijkl} can be calculated from the components of the stress and strain tensors.

$$C_{ijkl} = \left. \frac{\partial \sigma_{ij}}{\partial \epsilon_{kl}} \right|_{T, \epsilon_{kl}} = \left. \frac{1}{V_0} \frac{\partial^2 A}{\partial \epsilon_{kl}} \right|_{T, \epsilon_{ij}, \epsilon_{kl}} \quad (7)$$

317 where V_0 is the initial volume (undeformed) of the computed system, A is the
 318 Helmholtz free energy, σ and ϵ are the stress and strain components. Then bulk
 319 and shear modulus are obtained using Voigt–Reuss–Hill (VRH) approximation
 320 [68].

$$G_V = \frac{1}{15} [C_{11} + C_{22} + C_{33} + 3(C_{44} + C_{55} + C_{66}) - (C_{12} + C_{13} + C_{23})] \quad (8)$$

$$G_R = 15 [4(S_{11} + S_{22} + S_{33} - S_{12} - S_{13} - S_{23}) + 3(S_{44} + S_{55} + S_{66})]^{-1} \quad (9)$$

$$K_V = \frac{1}{9} [C_{11} + C_{33} + 2(C_{12} + C_{13} + C_{23})] \quad (10)$$

$$K_R = [S_{11} + S_{22} + S_{33} + 2(S_{12} + S_{13} + S_{23})]^{-1} \quad (11)$$

$$K_{VRH} = \frac{K_V + K_R}{2} \quad (12)$$

$$G_{VRH} = \frac{G_V + G_R}{2} \quad (13)$$

321 Finally, we can get the average Young's modulus (E) and the Poisson's ratio
322 (ν) by Eq. 14, 15:

$$E = \frac{9G_{VRH}}{3 + G_{VRH}/K_{VRH}} \quad (14)$$

$$\nu = \frac{3 - 2G_{VRH}/K_{VRH}}{6 + 2G_{VRH}/K_{VRH}} \quad (15)$$

Table 1: Fracture and elastic properties of different phases in matrix, ITZ and aggregates.

Phase	G_C (J/m ²)	K_{IC} (MPa · m ^{1/2})	K (GPa)	G (GPa)	E (GPa)	ν
C-S-H	1.81	0.349	44.10	17.82	47.10	0.32
CH	3.43	0.428	42.46	18.40	48.22	0.31
Quartz	8.60	0.904	38.97	42.85	94.06	0.10
C-S-H/Quartz	0.18	0.093	38.98	16.95	44.42	0.31
C-S-H/GO/Quartz	0.27	0.147	67.67	26.54	70.42	0.33
CH/Quartz	0.22	0.125	41.44	17.04	44.97	0.32
CH/GO/Quartz	0.38	0.173	63.88	27.27	71.62	0.31

323 3.2. Fracture properties of ITZ phase at nanoscale

324 After the simulation of the three representative phases in the cement matrix
325 and aggregate, our attention turns to the structure in the ITZ as this area is more
326 prone to failure and generally experiences cracks first compared to the matrix. To
327 replicate the fragile interfacial connection between cement matrix and aggregate
328 in ITZ, C-S-H and CH were individually in touch with quartz in the z-direction
329 to create an interfacial region with a thickness of around 10Å. Grand Canonical
330 Monte Carlo simulation was carried to introduce water molecules into the inter-
331 facial region. As an control, GO sheets were inserted into the interfacial system

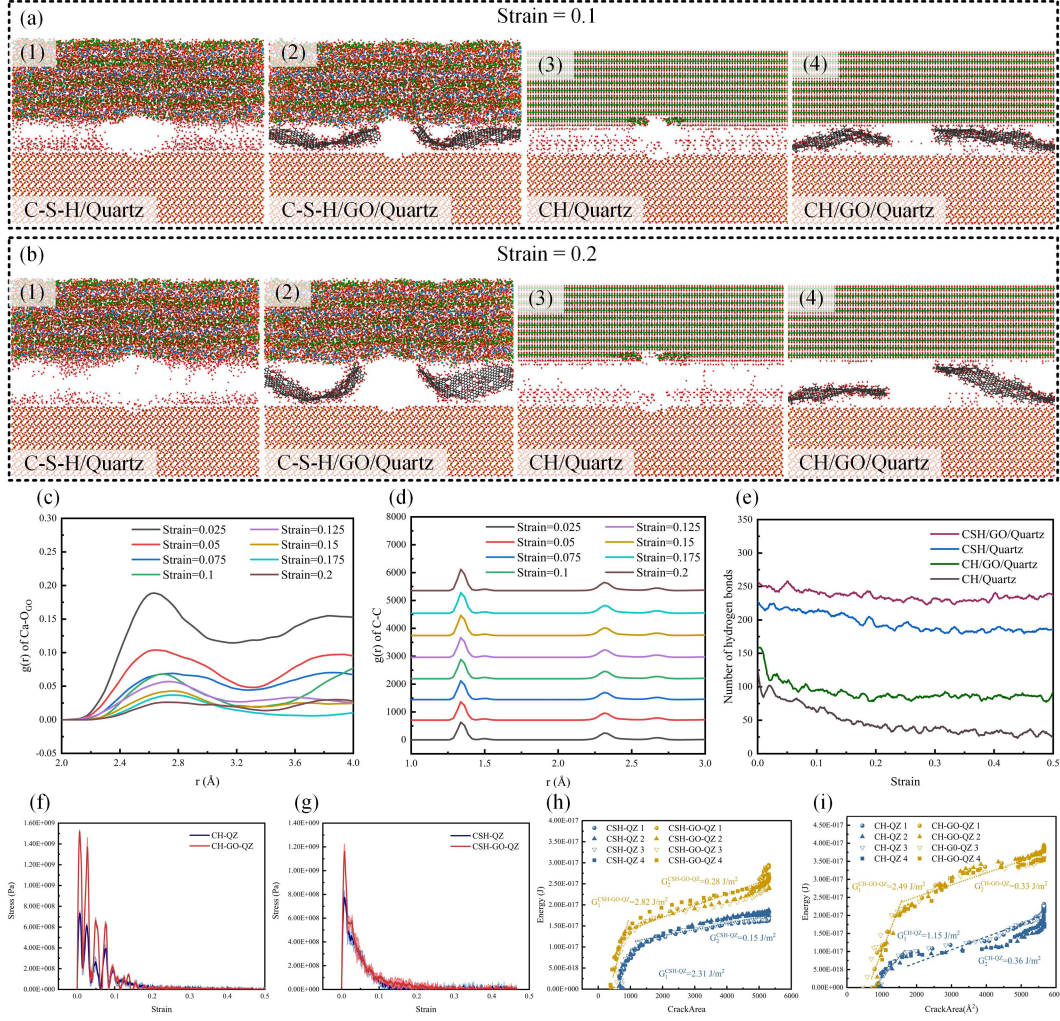


Figure 9: Simulation results of the interface between quartz and C-S-H, CH. Atomic snapshot of C-S-H/(GO)/quartz and CH/(GO)/quartz interfaces at (a) strain = 0.1 and (b) strain = 0.2. (c) Radial distribution function (RDF) of calcium atoms in the C-S-H phase and oxygen atoms in the GO sheet. (d) RDF of carbon atoms in the GO sheet. (e) The number of hydrogen bonds in the contacting interface during tensile deformation. Stress-strain curve of (f) CH/(GO)/quartz interfaces and (g) C-S-H/(GO)/quartz interfaces. Energy-crack area curve of (h) C-S-H/(GO)/quartz interfaces and (i) CH/(GO)/quartz interfaces.

(correspondingly reducing the number of water molecules) to simulate the effect of nano-fillers on ITZ enhancement and toughening.

The atomic snapshots for the four interfacial systems C-S-H/(GO)/quartz and

CH/(GO)/quartz at strains of 0.1 and 0.2 are shown in Fig. 9 (a) and (b). The yield strain of both C-S-H/quartz and CH/quartz decreases to roughly 0.007 under the impact of the poor interfacial bonding, which is in distinct contrast to 0.06 for the pure C-S-H phase and 0.1 for the CH phase. However, the addition of GO in the interfacial region plays a significant role in enhancing their ductility: the yield strain of C-S-H/GO/quartz and CH/GO/quartz increases to about 0.01 (see the stress-strain curve in Fig. 9 (f) and (g)). The improvement on the strength of adding GO in the interfacial system is more obvious, the yield strengths of C-S-H/(GO)/quartz and CH/(GO)/quartz system increases by 49.61% and 106.54%, respectively. This enhancement effect can be explained by the results of the RDF and hydrogen bond analysis [20]. Fig. 9 (c) illustrates the RDF of the Ca-O atom pair, where Ca is the intralayer and interlayer calcium atoms in C-S-H and O is the oxygen atoms in the carboxyl functional groups on the GO sheet. At a low strain of 0.025, the first peak of the Ca-O_{GO} pair appears near 2.63 Å. As the strain increases, the peaks are gradually shifted to near 2.79 Å (strain = 0.175) and finally there is almost no obvious peak value (strain of 0.2). At the same time, the peak also becomes to have a broader distribution with the increase of strain. This indicates that the originally stable Ca-O_{GO} connection in the interface is gradually elongated by the tensile deformation until finally there is no significant spatial correlation between Ca-O_{GO} pair [69]. The interactions between other atoms do not respond to strain in a way that the Ca-O pair does. This implies that the connection between calcium and oxygen in the interfacial system plays the most dominant role in resisting deformation and crack. For instance, the RDF curve for the C-C pair (Fig. 9 (d)) shows no sensitive changes to strain, with only a small increase of the peak value caused by the bending of the GO sheet during deformation.

The hydrogen bonds in the interface region, in addition to the atomic interactions between Ca and O_{GO}, also play an important role in the resistance to tension. Fig. 9 (e) shows the curves of the number of hydrogen bonds with strain in the four interfacial systems. In the C-S-H/(GO)/quartz system, there are 64.74% ~ 77.34% more hydrogen bonds than in the CH/(GO)/quartz system. This difference can be attributed to the C-S-H phase's rougher surface and a large number of free hydroxyl groups, which enable the C-S-H phase to form more hydrogen bonds with GO. The addition of GO to the interface considerably increases the number of hydrogen bonds even though the amount of oxygen atoms in GO is much less than the oxygen atoms of water molecules in the interface without GO. Finally, The critical energy release rate and fracture toughness for the four interfacial systems were determined, as in the previous section, by tracking the energy

versus crack area of the system. These results, together with other elastic property parameters, are reported in Table 1. Fig. 10 (a) shows the fracture toughness of C-S-H/CH/(GO)/quartz composites phases. Compared to the results of Bauchy et al. [66] and Zhang et al. [65], the fracture toughness of C-S-H with a C/S of 1.7 in this paper is slightly lower than that of the reference sample with a C/S ratio of 1.65. This is mainly due to the fact that the increase in the C/S ratio leads to more defects in the silicate tetrahedron chains, and the decrease in the average chain length leads to a corresponding decrease in the fracture properties of C-S-H [70, 71]. The addition of GO increased the fracture toughness of the C-S-H/quartz and CH/quartz systems by 58.06% and 38.40%, respectively. The MD approach used to calculate the fracture parameters in this paper is applicable to other similar cementitious composite systems. As shown in Fig. 10 (b), nanoscale simulations can also be used to examine the polymer-reinforced concrete system represented by the C-S-H/resin interface and investigate how the material design approaches affect the system's fracture response.

3.3. Fracture simulation at macroscale

Due to the limitations of computational resources, many reported studies ignore the effect of ITZ in macroscopic models or simply set the mechanical properties of ITZ as a linear reduction of the cement matrix [72, 73, 74]. Pores in the cement matrix and ITZ must be taken into account in order to upscale the mechanical properties of the individual phases from microscopic to macroscopic. The different phases that correspond to the MD simulations will therefore be treated as porous materials and homogenized using Eq. 16, 17, 18, 19 given by the Mori-Tanaka method [75].

$$K_{hom} = \frac{\sum_i V_i K_i \left(1 + A_r \left(\frac{K_i}{K_r} - 1\right)\right)^{-1}}{\sum_i V_i \left(1 + A_r \left(\frac{K_i}{K_r} - 1\right)\right)^{-1}} \quad (16)$$

$$G_{hom} = \frac{\sum_i V_i G_i \left(1 + B_r \left(\frac{G_i}{G_r} - 1\right)\right)^{-1}}{\sum_i V_i \left(1 + B_r \left(\frac{G_i}{G_r} - 1\right)\right)^{-1}} \quad (17)$$

$$A_r = \frac{3K_r}{3K_r + 4G_r} \quad (18)$$

$$B_r = \frac{6K_r + 12G_r}{15K_r + 20G_r} \quad (19)$$

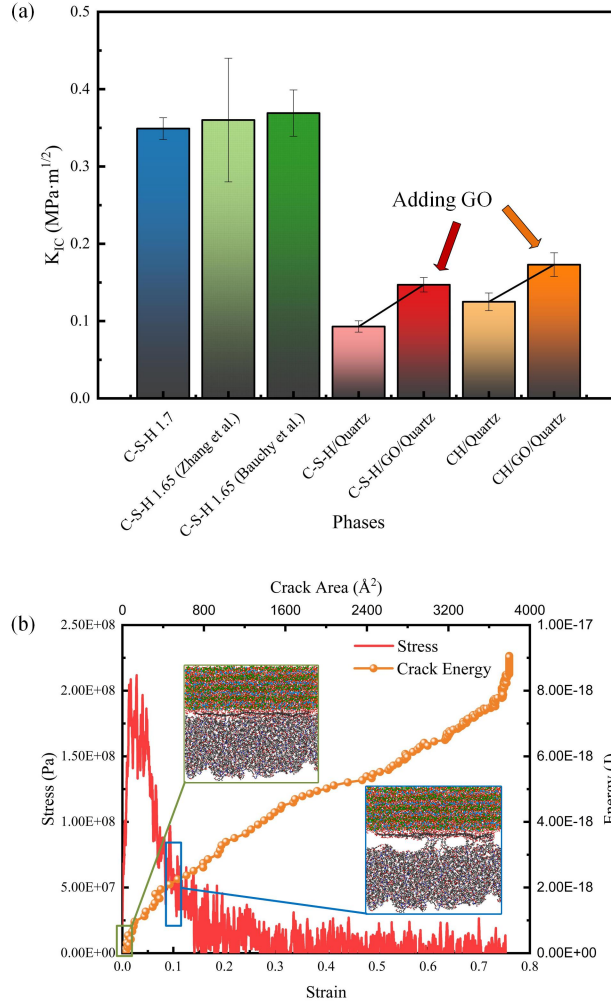


Figure 10: Fracture toughness of different phases (a) and extended application of the fracture properties tracking method in this article to the resin/cement composites system (b).

397 The volume fraction of cement paste components can be written as a function
 398 of w/c according to the empirical equations [76]:

$$f_{clin}(\xi) = \frac{1 - \xi}{1 + \frac{\rho_{clin}}{\rho_{H_2O}}(w/c)} \quad (20)$$

$$f_{H_2O}(\xi) = \frac{\rho_{clin}(w/c - 0.42\xi)}{\rho_{H_2O} \left[1 + \frac{\rho_{clin}}{\rho_{H_2O}}(w/c) \right]} \quad (21)$$

$$f_{hyd}(\xi) = \frac{1.42\rho_{clin}\xi}{\rho_{hyd} \left[1 + \frac{\rho_{clin}}{\rho_{H_2O}}(w/c) \right]} \quad (22)$$

where f_{clin} , f_{H_2O} , f_{hyd} are the volume fractions of clinker, water, and hydration products, respectively. ξ ($0 \leq \xi \leq 1$) is the degree of hydration. Fig. 11 shows a schematic diagram of the RVE for cement paste only in several different hydration states. In order to facilitate the subsequent calculation and unified discussion, here we take RVE for the fully hydrated cement paste with $w/c=0.42$ for finite element simulation calculation.

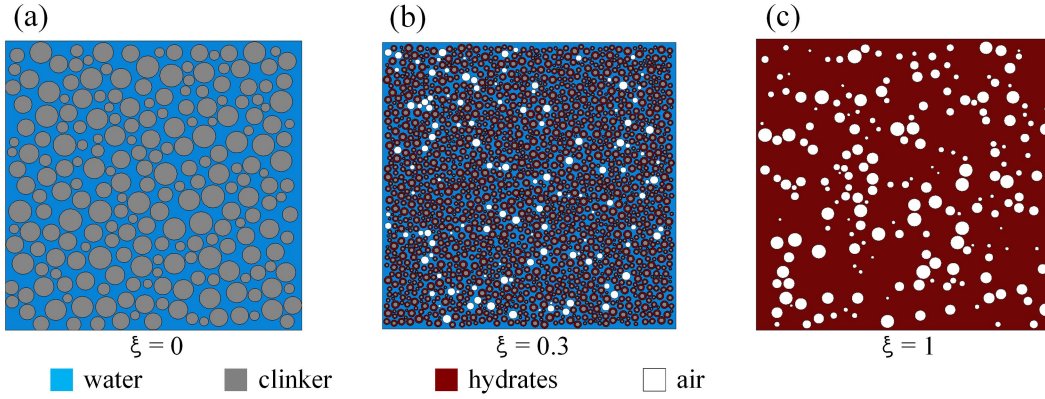


Figure 11: Changes in the composition of cement paste at different degree of hydration.

Table 2: Volume ratio and porosity of different components in RVE of matrix.				
Level	Phase	Density (g/cm^3)	Porosity	Volume
C-S-H solid	Globules	2.39	0.18	-
C-S-H gel	LD-C-S-H	1.93	0.52	0.67
	HD-C-S-H	2.13	0.237	0.25
CH	CH	2.24	0.28	0.08

Fig. 12 (a) shows a FEM model of cement paste only. As mentioned above, at hydration state $\xi = 1$ and $w/c=0.42$, we can assume that clinker in cement paste

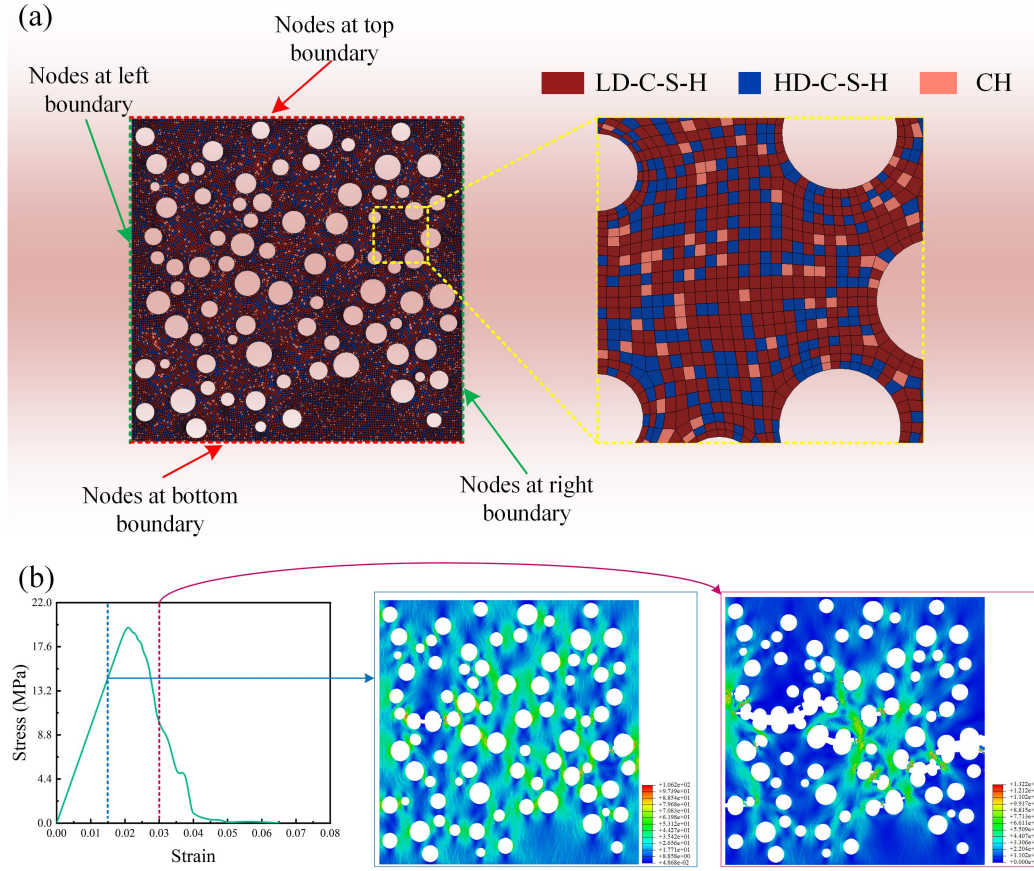


Figure 12: (a) FEM model of cement paste RVE and composition distribution. (b) Stress-strain curve of RVE and stress distribution at strain = 0.015, and 0.03.

Table 3: Elastic and cohesive parameters of different phases in cement matrix for ABAQUS.

Materials	E (GPa)	G_{12} (GPa)	ν	Fracture Energy G_n^C (N/mm)	σ_n^0 (MPa)	σ_{st}^0 (MPa)
LD-C-S-H	13.55	27.10	0.27	5.54	35.46	70.91
HD-C-S-H	19.37	38.75	0.28	7.92	50.69	101.37
CH	19.07	38.14	0.27	12.15	88.21	176.42

407 reacts completely with water, leaving only C-S-H, CH and porosity. According to
408 the volume fraction and porosity of each phase such as high density (HD) and low

409 density (LD) C-S-H in references [72] (see Table. 2), based on the Mori-Tanaka
 410 scheme and micromechanics theory we get the results of parameters after the first
 411 step of the homogenization [77, 76, 78], as shown in Table. 3. Scale bridging
 412 simulations using continuum theories usually need selecting a sub-volume of RVE
 413 from a large bulk material and applying periodic boundary conditions to simulate
 414 the overall elasticity and damage evolution of the bulk material [79, 80, 81, 82].
 415 Here, we build the PBC for cement paste RVE model by applying the constraint
 416 equation as follows.

$$u_x^{Left} - u_x^{Right} = 0 \quad (23)$$

$$u_y^{Top} - u_y^{Bottom} = \Delta u \quad (24)$$

417 Eq. 23 and 24 can be implemented by applying constraints to the nodes on the
 418 four edges of the model, as Eq. 25:

$$A_1 u_i^P + A_2 u_j^Q + \dots + A_N u_k^R = \hat{u} \quad (25)$$

419 where N is the number of nodes on an edge, A_N is a constant coefficient of
 420 nodes' relative motion. i, j, k represent degree of freedom and $\hat{u}$ is the displace-
 421 ment of a dummy node, on which we can apply load on it.

422 Stress-strain curve of RVE is shown in Fig. 12 (b). The tensile stress in the
 423 RVE reaches a peak of 19.46 MPa at strain=0.02, however some of the elements
 424 have broken down and formed cracks which bridging two adjacent pores before
 425 the strain reaches 0.015. As the strain continues to increase, the number of cracks
 426 linking multiple pores gradually increases and tends to form penetration cracks
 427 through the entire model section. Finally, it breaks completely at strain=0.065
 428 and the stress is reduced to zero. Since there are rare direct uniaxial tensile ex-
 429 periments on micro-scale cements, we refer to indirect tensile strength values ob-
 430 tained from flexural strength test and split tensile strength test in previous studies.
 431 Generally these indirect tensile strength values are not equal to the direct uniax-
 432 ial tensile strength values, and split tensile tests tend to underestimate the actual
 433 strength values [83]. Moreover, the size of the specimen has a very strong influ-
 434 ence on the tested strength values, the strength measured at the micro-scale can
 435 even be an order of magnitude higher than that tested on macro specimen [19].
 436 Most of the split tensile strengths of cement paste reported in the literature are in
 437 the range of 3.56 MPa - 6.90 MPa [84, 85, 86, 87, 88], and most of the flexural
 438 strengths are in the range of 9.35 - 14.15 MPa [84, 19, 89, 90].

Even considering the underestimation of the experimental values, the tensile strength value of cement paste obtained from the simulations in this paper are still large. The overestimation of the tensile strength values in this paper is mainly affected by the following factors: 1. In order to simplify the modeling, the tendency of the distribution of C-S-H, CH and pores is not taken into account. C-S-H tends to be more concentrated in the periphery of the cement particles, and CH is more likely to be generated in the vicinity of pores and have preferential orientations. This morphological feature leads to inhomogeneous distribution of the strength and stiffness. In this study we randomly and uniformly distribute LD-C-S-H, HD-C-S-H, CH with pores, this idealized model is significantly different from the real cement paste morphology. 2. The finite element models in this paper was assumed that the specimens have $w/c = 0.42$ and are fully hydrated. Specimens cured for 28 d or earlier are often used for experimental tests, which have the strength values at least 30% lower than those of fully hydrated specimens [88]. The focus of this paper is on how to predict the effect of adding nano-additives on the tensile fracture properties of cementitious composites, and a side-by-side comparison of the predictive models considering with or without nano-additives, and the addition of different types of nano-additives, may be more meaningful for this multiscale model. This in turn guides researchers to design composites with better performance of toughness and crack resistance.

Table. 4 shows the volume ratios occupied by pores and four phases that correspond to the MD simulation in the cement matrix or ITZ. On the other side, the aggregates are envisioned as dense, voidless structure. There are higher porosity and more CH products in the ITZ compared to the matrix, which is consistent with the reported experimental results [77, 52]. For example, the CH to C-S-H ratio in the cement matrix is 8:77. The elements in the matrix region of the FEM model are randomly assigned the material properties of CH or C-S-H according to that ratio after homogenization of CH and C-S-H with a 15% porosity.

Table 4: Volume ratio of different components in cement matrix and ITZ.

Components	matrix	ITZ
Pores	15%	30%
CH	8%	-
C-S-H	77%	-
CH/(GO)/quartz	-	13%
C-S-H/(GO)/quartz	-	57%

Similar to the homogenization of the different components in cement ma-

trix, we also calculated the parameters of the main components of ITZ, C-S-H/(GO)/Quartz and CH/(GO)/Quartz, as listed in Table. 5. Then the second step of multi-phase homogenization was carried out to get the parameters of overall properties for cement matrix, ITZ, and aggregate. These three materials were used in the single-aggregate and multi-aggregate FEM model, which will be discussed in the following paragraphs. Two types of elements were used in ABAQUS: 4-node bilinear element for elastic materials, and two-dimensional cohesive element with four nodes for materials with damage of traction-separation law. The parameters applied for all different phases in the cohesive elements were listed in Table. 6. The Young's modulus (E) and Poisson's ratio (ν) of elastic materials were set to the same values as in the cohesive elements. Since the bond strength between the C-S-H layers is much smaller than the bond parallel to the direction of the SiO_4 tetrahedral chains, in this paper we considered the tensile properties when the loading direction is perpendicular to the C-S-H layers, to take the most fragile case in matrix and ITZ into account. However, the orientation of the C-S-H layer in actual cementitious materials is of random nature and will not be always perpendicular to the loading direction. Furthermore, too small shear strength will lead to larger distortion of the FEM model cells under uniaxial tensile loading, which is more difficult to converge. We set the shear modulus and strength to be twice that of normal direction, and such an approximate treatment will greatly reduce the difficulty of model convergence.

Table 5: Elastic and cohesive parameters of different phases in ITZ for ABAQUS.

Materials	E (GPa)	G_{12} (GPa)	ν	Fracture Energy G_n^C (N/mm)	σ_n^0 (MPa)	σ_{st}^0 (MPa)
C-S-H/Quartz	7.73	15.47	0.25	0.22	5.20	10.39
C-S-H/GO/Quartz	12.27	24.55	0.26	0.41	9.22	18.43
CH/Quartz	7.83	15.67	0.26	0.26	5.81	11.63
CH/GO/Quartz	12.47	24.95	0.26	0.43	12.01	24.03

The single-aggregate model's stress distribution contours at three deformation (strain = 0.05, 0.1, and 0.15) is shown in Fig. 13. The stress distribution (max principal Stress) and damage state (damage variable D) for the models with and without GO modified ITZ are displayed in order to illustrate the features of local cracks. It can be seen that no cracks appear in both the pure sample and the GO-modified ITZ sample at low strains (damage variable in the legend is zero at strain = 0.05). There is a distinct stress concentration zone, that tends to extend

Table 6: Elastic and cohesive parameters of single/multi-aggregate models for ABAQUS.

Materials	E (GPa)	G_{12} (GPa)	ν	Fracture Energy G_n^C (N/mm)	σ_n^0 (MPa)	σ_{st}^0 (MPa)
Cement	9.69	19.38	0.25	3.15	20.13	10.39
ITZ without GO	4.17	8.33	0.24	0.30	6.67	18.43
ITZ with GO	6.62	13.23	0.24	0.61	13.89	11.63
Aggregate	31.65	63.30	0.14	51.43	123.43	24.03

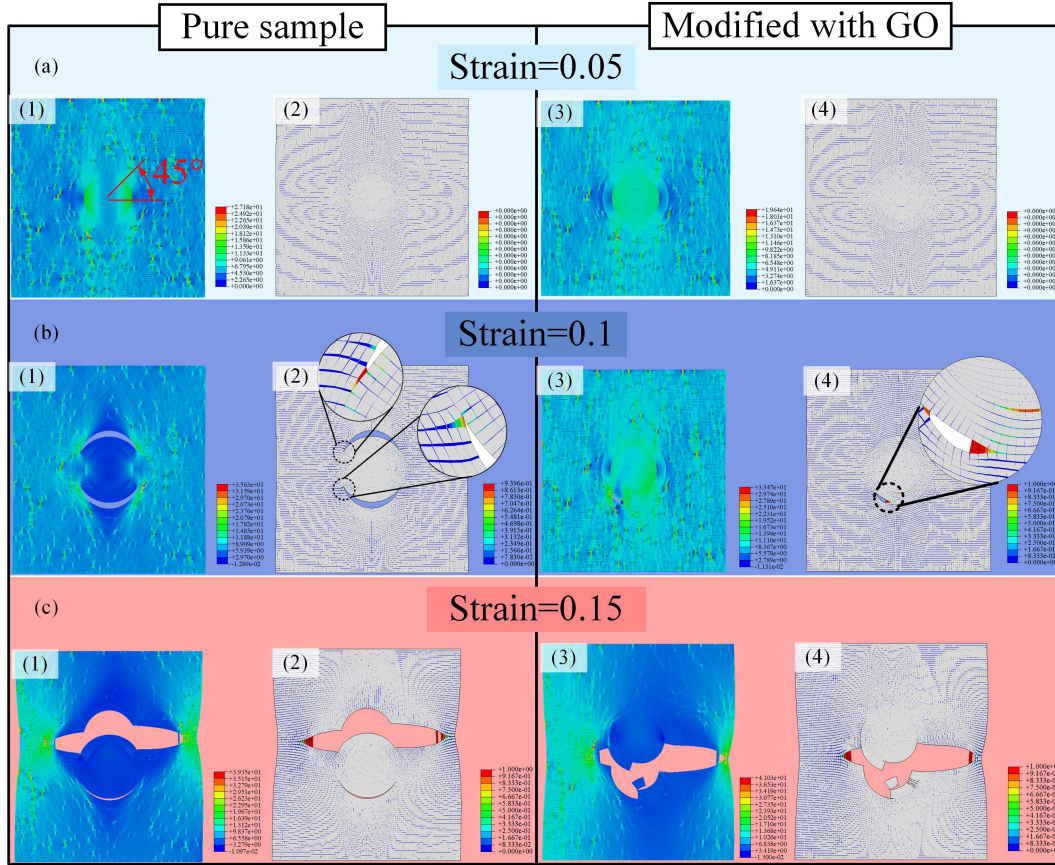


Figure 13: Stress distribution and damage status of the representative volume element model at strain = (a) 0.01, (b) 0.02, and (c) 0.03.

496 into the matrix at a angle of 45° , in the ITZ region of the pure sample. However,
 497 in the GO-modified ITZ sample, the concentration of stress is not obvious in the

ITZ region, and the stress is transmitted almost throughout the model from top to bottom along the high stiffness aggregate particle. It suggests that the addition of GO reduces the stiffness gap between ITZ and aggregate, allowing for more homogeneous distribution of stress [14, 15, 27]. As can be observed from the enlarged view in Fig. 13 (b), at a strain of 0.1, the upper and lower surfaces of the aggregate in the pure sample have been cracked extensively and the cracks start to penetrate into the matrix. At the same time, the GO-reinforced ITZ sample only exhibits brand-new cracks in the ITZ.

At the strain of 0.15, both the pure sample and the GO-modified sample are on the brink of full fracture. It is clear that the pure sample really cracks along the 45° angle of stress concentration in the ITZ, and expands into the matrix along the left and right sides of the horizontal direction simultaneously until it penetrates the whole model. In contrast, the lower surface of the aggregate in the GO-modified ITZ sample exhibits damage throughout the entire ITZ, and the horizontal crack expansion in the matrix lags behind that of the pure sample. The ITZ no longer neatly cracks along the contact surface with the matrix or aggregate, but instead assumes a portion of the resistance to crack expansion. This crack path through the ITZ indicates that GO does enhance the ITZ's fracture toughness. The increased tensile strength and maximum strain of the GO-modified samples are a result of ITZ's enhanced toughness. The global stress-strain curve of single-aggregate model in Fig. 14 (a) shows that the stress of pure sample suddenly decreases when the strain reaches 0.075. It then continues to rise until it reaches the maximum stress (22 MPa) at strain of 0.133, followed by significant brittle damage and finally complete fracture at strain of 0.156. The GO-reinforced ITZ sample, on the other hand, exhibits a higher tensile elasticity modulus (234 MPa), a higher peak stress (27 MPa), and a higher maximum strain (0.17). It's worth mentioning that the "global stress-strain" in this study means the value of force applied on the loaded reference point divided by the cross-sectional area of the model, and the displacement of the reference point divided by the side length of the model.

In the multi aggregate concrete model, the maximum strain substantially decreases and the global stress-strain response becomes more brittle (see Fig. 14 (b)) due to the significant increase in the volume ratio of aggregates and ITZ [91]. As the volume fraction reaches a critical value, the strength of concrete decreases with increasing volume fraction, which is related to the weak adhesion between the aggregate and the matrix [92, 93]. A higher aggregate volume fraction means there will be more aggregate-matrix interfaces, which have a large number of pores and microcracks [94]. And fine aggregates' absorption of surrounding wa-

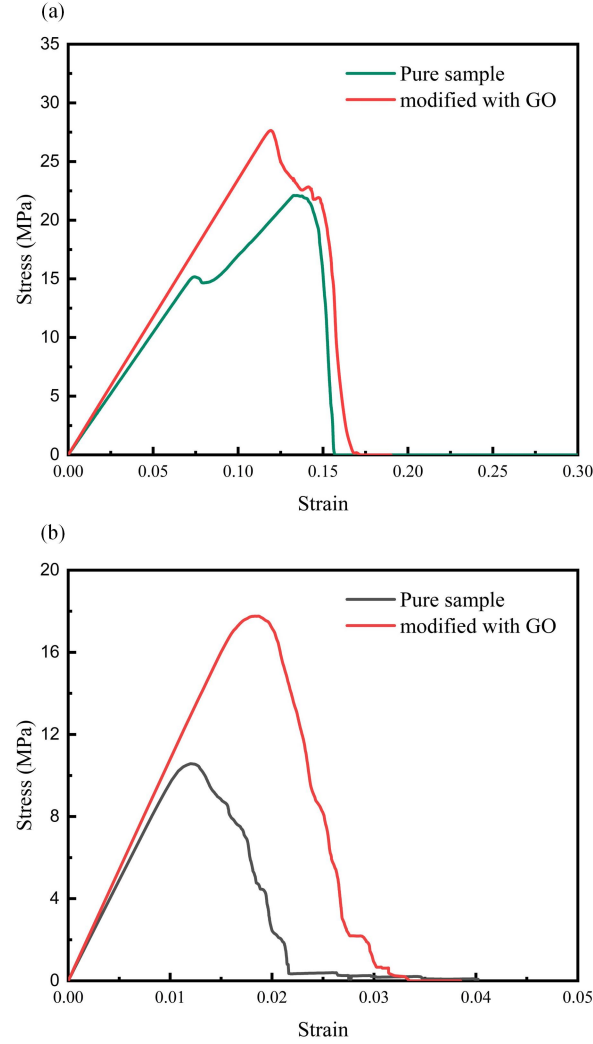


Figure 14: Stress-strain curves of (a) the representative volume element FEM model and (b) the multi aggregate concrete FEM model.

536 ter may negatively affect the mechanical bonding at the interfacial transition zone
 537 [95]. In Fig. 15 the stress distribution and damage evolution results at strains of
 538 0.01, 0.02, and 0.03 are chosen and compared. The pure concrete sample with-
 539 out GO modification exhibits noticeable stress concentration around the aggregate
 540 particles under tension. The low stress zones in the core of the aggregates indi-
 541 cate that the sudden change in stiffness and strength near the aggregates hinder

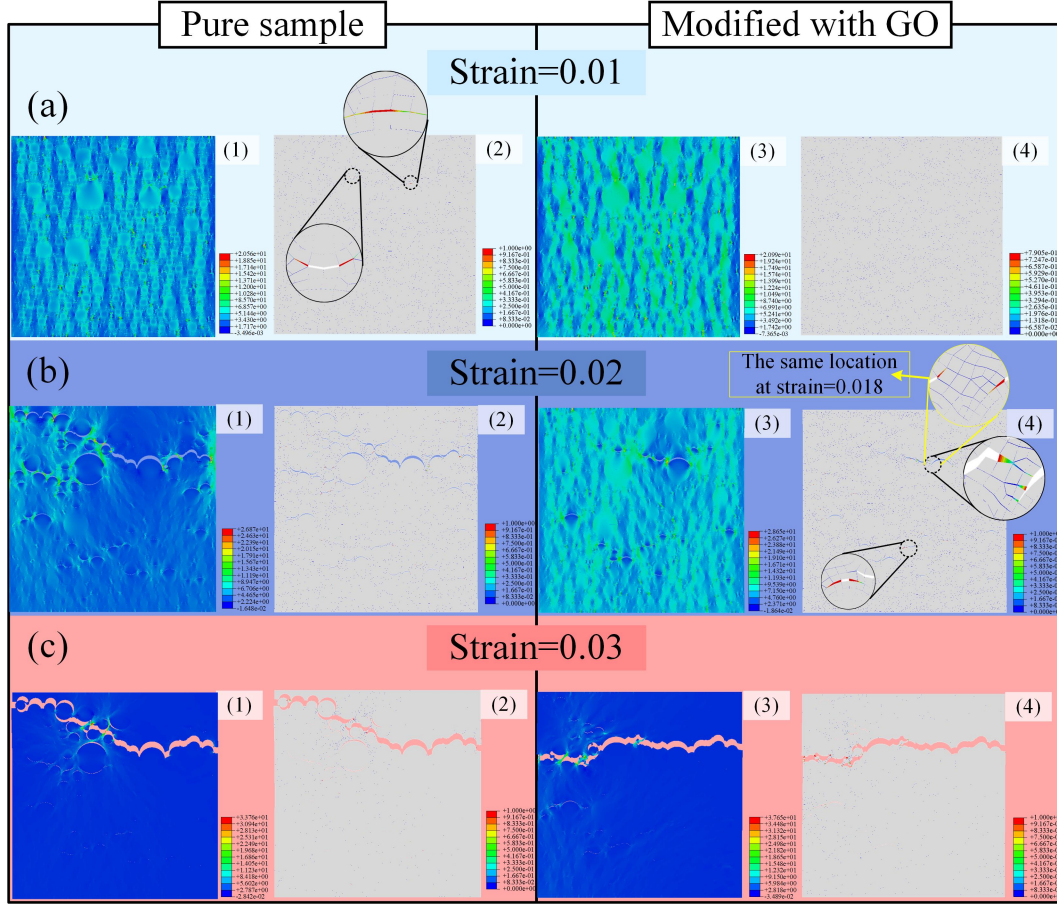


Figure 15: Stress distribution and damage status of the multi aggregate concrete FEM model at strain = (a) 0.05, (b) 0.1, and (c) 0.15.

the transmission of stress, due to the poor mechanical properties of ITZ. The pure concrete sample shows tiny amounts of localized elements' failure, even at a low strain of 0.01 (see Fig. 15 (a1, a2)), but this does not seem to be sufficient to cause an overall stress drop [96] (the peak stress (10 MPa) is reached latter at a strain of 0.012). In contrast, the stresses are more effectively transmitted between the aggregates in the GO-reinforced concrete model, leading to numerous stress bands that run parallel to the axis of the strain. At a strain of 0.01 (Fig. 15 (a3, a4)), a very tiny portion of the elements exhibited stiffness degradation, but no initial cracks were formed. When the strain reaches 0.02, the stress in the pure concrete sample has decreased to 34.75% of the maximum strength, and it is al-

552 most entirely concentrated in the ITZ near the existing cracks, see Fig. 15 (b1). In
 553 Fig. 15 (c1) we can see that, the value of stress in the region away from the cracks
 554 is extremely low or even close to zero. Massive cracks were first formed around
 555 all the aggregates with large particle sizes ($d \geq 10mm$), and gradually extended
 556 to other adjacent aggregate surfaces to form continuous cracks through the model
 557 (see Fig. 15 (c1, c3)). The strain in the GO-modified concrete model was 0.018
 558 when the stress reached its peak (18 MPa), the cracks just started to form on the
 559 upper and lower surfaces of the aggregates, as shown in enlarged view of damage
 560 status in Fig. 15 (b4). The extensive stress concentration region at the end of
 561 cracks implies that the GO-reinforced ITZ has a considerable blunting impact on
 562 the crack tips [97], and the crack therefore has not yet penetrated into the matrix
 563 to form continuous cracks going through multiple aggregates [98]. Both pure and
 564 GO-modified concrete models were on the verge of complete damage at a strain of
 565 0.03. In contrast to the pure concrete model, the cracks in the GO-modified con-
 566 crete model took a different path, and as shown in Fig. 15 (c), the GO-modified
 567 concrete samples still had quite a bit of ITZ and matrix attached to the sides of
 568 the cracks after the cracks penetrated the entire section. These adherent regions
 569 improved the toughness of the GO-modified concrete sample, allowing a larger
 570 maximum strain than the pure concrete model (as shown in Fig. 14 (b)).

571 **4. Conclusions**

572 In this paper, a multiscale model of cementitious composites considering ITZ
 573 was constructed by molecular dynamics simulation and finite element method.
 574 The fracture mechanical properties of different phases (C-S-H, CH, quartz, and
 575 GO) and their interfacial composites were investigated. The bottom-up design of
 576 concrete materials was attempted by exploring the enhancement of GO on ITZ
 577 utilizing the key parameters of nanostructures as input parameters of the finite
 578 element model.

579 The fracture toughness and energy release rates of matrix, ITZ, and aggregate
 580 at nanoscale was determined by molecular dynamics simulation. The energy re-
 581 lease rate of the ITZ structure decreased to 6.41% $\sim$ 9.94% of C-S-H and CH
 582 due to the poor interfacial bonding between the different phases. By adding GO
 583 sheets into the interface, the ITZ system's fracture toughness was increased by
 584 38.40% $\sim$ 58.06%. The better plastic deformation capacity of the GO-modified
 585 ITZ structure is primarily attributed to the atomic interaction between the Ca
 586 atoms and oxygen-containing functional groups on the GO sheet and the hydrogen
 587 bonds in the interface.

In both single-aggregate and multi-aggregate finite element models, GO-modified ITZ resulted in more uniform stress transmission near the aggregates, as well as wider and more continuous stress bands along the strain direction. In the case of continuous cracks generated between aggregate particles, the GO-modified ITZ was effective in delaying the crack extension into the matrix and forming a blunting region at the crack tips. The GO-modified concrete model showed an 80% increase in tensile strength and a 9.81% increase in tensile modulus.

These findings highlight the potential of using nanoscale design to optimize the mechanical properties of cementitious composites, particularly through the incorporation of GO into the ITZ. This study provides valuable insights into the bottom-up design of concrete materials and paves the way for future research on the development of advanced cementitious composites with enhanced mechanical properties for a wide range of applications.

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