Brain-Computer Interface in Stroke Rehabilitation

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Abstract
Recent advances in computer science enabled people with severe motor disabilities to use brain-computer interfaces (BCI) for communication, control, and even to restore their motor disabilities. This paper reviews the most recent works of BCI in stroke rehabilitation with a focus on methodology that reported on data collected from stroke patients and clinical studies that reported on the motor improvements of stroke patients. Both types of studies are important as the former advances the technology of BCI for stroke, and the latter demonstrates the clinical efficacy of BCI in stroke. Finally some challenges are discussed.

Category: Human computing

Keywords: Stroke; Rehabilitation; Brain-Computer Interface; Motor Imagery, Electroencephalography

I. INTRODUCTION
Stroke occurs when blood supply to the brain is blocked or when blood vessels in the brain burst. About 15 million people worldwide suffer from stroke every year [1]. One in 20 adults (aged >14 years) in the developed countries is affected by stroke [2]. Stroke is a major cause of disability and it affects the quality of life of the survivors in their daily functioning in the workplace, home, and community. Recovery of the motor function after stroke is crucial in order to perform activities of daily living, but this recovery is often variable and incomplete [3]. The main mechanism underlying motor recovery involves enhanced activity of the primary motor cortex induced by Active Motor Training (AMT) and pharmacological interventions [4]. Clinical studies of AMT such as constraint-induced movement therapy (CIMT) improve outcome after chronic stroke, but poor motor performance excludes most of the otherwise eligible acute stroke patients from CIMT [5]. Hence, the clinical use of AMT is limited by a dependence on residual motor performance.

Since physical movements by stroke patients are often not possible, alternate strategies are needed. Motor imagery (MI), the mental rehearsal of physical movement tasks, represents a new approach to access the motor system and rehabilitation at all stages of stroke recovery [6]. Unlike AMT, MI is not dependent on residual motor performance, and direct cellular recording of primate has shown that the primary motor cortex (M1) is involved during MI [7]. A functional imaging study in subcortical stroke had shown that the motor system is activated during MI despite the lesion [8]. Since stroke does not impair the capacity to perform MI [9, 10], MI provides a substitute for AMT as a means to activate the motor network in stroke [6]. However, while AMT can be observed, MI is concealed within the patient. Thus it is difficult to assess the performance of MI non-invasively without involving functional magnetic resonance imaging (fMRI), positron emission tomography (PET), near infrared spec-
II. BCI IN STROKE

A BCI is a computer-based system that translates brain signals into commands for an output device to perform a desired action. A stricter definition of BCI is limited to systems that only use signals from the central nervous system (CNS), and systems that are voice or muscle-activated are not considered BCI [13]. As such, the main interest in BCI technology is to help people who suffered from neurological disorders such as amyotrophic lateral sclerosis, stroke or other traumatic brain disorders [12].

III. REVIEWS ON BCI

There are currently several recent reviews of BCI in the literature. The recent review by Nicolas-Alonso and Gomez-Gil [15] comprehensively covered the different BCI modalities, such as EEG, MEG, fMRI, NIRS, electrocorticography (ECoG), and intracortical neuron recording. This review also broadly discussed how certain neurophysiological signals can be used to determine dependent brain plasticity of the stroke survivors by paying close attention to a motor task that required the activation or deactivation of specific brain signals.

The theory behind AMT in stroke rehabilitation is called CIMT [5]. This theory is based on the idea of “learned non-use”, which develops during the early stages of the stroke survivor to compensate for difficulty in using the impaired limb from increased reliance on the intact limb. Rehabilitation therapy thus involves immobilizing the intact limb while the stroke survivor is trained to use the impaired limb. The theory behind BCI stroke rehabilitation is similar to CIMT, but the difference lies in focusing on thoughts of moving the impaired limb instead of physically moving the impaired limb. This is called MI, which is the mental rehearsal of physical movement tasks. For many stroke patients, moving the impaired limb is very difficult and sometimes impossible even after early participation in an active rehabilitation program. Thus MI can be used to perform repetitions of movement at the cerebral level without any physical demands [14]. In other words, the intervention from AMT is primarily targeted at the stroke impaired limb, whereas the intervention from MI is primarily targeted at the stroke impaired brain. Since the performance of MI is not dependent on any residual motor performance of the impaired limb, this represents an alternate approach [6]. There is scientific evidence that the primary motor cortex is involved during MI as well as motor execution (ME), thus the capacity to perform MI is not impaired by stroke and may be substituted for ME as a means to activate the motor network in stroke. However, ME can be checked by observation, whereas MI is concealed within the patient. Nevertheless, BCI can be used to objectively assess the performance of MI. Neurophysiologists have shown that the performance of MI and ME result in compression of the µ- or β-rhythms in EEG brain signals. This phenomenon is known as event-related synchronization (ERS) or event-related desynchronization (ERD), and various BCI-based have been developed to detect this from EEG during MI. The challenge arises in the detection of MI due to the low signal-to-noise ratio, and recent advances in signal processing and machine learning methods have enabled the clinical deployment of BCI for stroke rehabilitation.
the user intentions, such as visual evoked potentials (VEPs), slow cortical potentials (SCPs), P300 evoked potentials, and sensorimotor rhythms. In addition, the review also presented some feature extraction and classification techniques used in BCI applications that translate information in the control signals into commands to operate a computer or other device, and provided an overview of various BCI applications that control a range of devices.

Another review by Shih et al. [13] discussed the application of BCI in the field of Medicine, and stated three critical areas of development in the future of BCIs: comfortable, convenient, and stable signal-acquisition hardware; BCI validation and dissemination; and proven BCI reliability and value for various user populations. Silvoni et al. [16] presented a review on the history of BCI research in stroke up to 2011, and classified BCI-based rehabilitation into three approaches: substitutive strategy, classical conditioning and operant conditioning. In addition, they also presented their pilot study of a new neuro-force feedback strategy on healthy subjects.

The review by Silvoni et al. [16] is one of the most comprehensive reviews on the progress of BCI in stroke up to 2011, and also covered works that reported on healthy subjects, patients with spinal cord injury (SCI) and amyotrophic lateral sclerosis (ALS). Since 2011, there is a significant increase in the research of BCI in stroke. Thus we review works up to 2013, focusing only on works that reported data collected from stroke.

IV. RECENT WORKS OF BCI ON STROKE PATIENTS

Table 1 presents a review on studies of BCI on stroke in a chronological order. A search revealed numerous papers of BCI for stroke, but only those papers that reported work on data collected from stroke patients are included in this review. These studies are classified into the type BCI modalities (EEG, MEG, NIRS as well as any other signals such as eye trackers or stimulation such as transcranial direct current stimulation (tDCS)) and type of BCI feedback (visual, robot, orthosis, functional electrical stimulation (FES)). In addition, the number of stroke patients included in these studies, the type of task (MI or ME), the targeted stroke-affected disability (hand, upper limb, lower limb, ankle), and whether physical therapy is included are summarized. Most importantly, the types of motor assessment used to evaluate the effectiveness of the BCI intervention are summarized. In addition, whether randomized control trials (RCT) were conducted, the most rigorous way of evaluating an intervention and its effectiveness [17] is indicated. Furthermore, any other evidence in neuroimaging that showed the effectiveness of the BCI intervention is also summarized. Finally, works that reported on data collected from the same clinical study are annotated.

A. Methodology Studies

The first attempt to use BCI in motor rehabilitation [16] was presented by Pfurtscheller et al. [18] on a patient who suffered from traumatic spinal cord injury, but not on one who suffered from stroke. Subsequently, the first study of BCI on stroke patients [16] was first reported by Mohapp et al. [19]. This study focused on extracting relevant features from EEG of stroke patients from performing MI and ME of hand. We classified such a study as methodology studies, which focused more on the methodology than the motor outcome. Methodology studies are important as they advance the technology of BCI in stroke. Similarly, Bai et al. [20] reported the performance of a sensorimotor β-rhythm-based BCI with visual feedback but without BCI training on a stroke patient. The other difference between this study and the first study was that visual feedback was employed, which is an important aspect of BCI.

Subsequently, there was an increase in the number of papers that reported methodology studies on stroke patients [21-31], and henceforth we will only briefly highlight some of these studies that we found exhibited distinctiveness from other studies. Besides targeting the hand and the upper limb functions, Niazi et al. [23] reported a study on 5 stroke patients targeting ME of the lower limb ankle function. Although this study used a BCI system that was muscle-activated and thus strictly not considered a BCI [13], this was the first study on stroke patients that targeted one of the other four MI actions other than left and right upper limb [32]. Tam et al. [24] and subsequently Arvaneh et al. [25, 26] presented methods that specifically reduced the number of EEG electrodes of MI BCI for stroke subjects. Using BCI with a large number of channels involves a longer preparation time that directly impacts the convenience of stroke patients using BCI for rehabilitation. These two works thus directly addressed this issue, which is essential in the use of BCI for stroke patients in the clinical setting.

B. Clinical Studies

The very first clinical study of using BCI on stroke patients was presented by Buch et al. [33]. In this study, 8 patients modulated their m-rhythm to control a screen cursor using a MEG-based BCI. Although 6 out of 8 were successful in controlling the screen cursor linked to an orthosis attached to the stroke-affected hand, no significant improvements in motor outcome were reported using the Medical Research Council (MRC) scale. We classified such a study that reported clinical measures in motor outcome as clinical studies. Clinical studies are very important as they demonstrate the clinical efficacy of BCI in stroke.

Next, Ang et al. [34] reported preliminary outcome of an RCT to investigate the outcome of MI BCI robotic
Table 1. Studies of brain-computer interface (BCI) on stroke patients

<table>
<thead>
<tr>
<th>Study</th>
<th>BCI modality</th>
<th>RCT</th>
<th>Stroke population</th>
<th>Task</th>
<th>Target</th>
<th>PT</th>
<th>BCI feedback</th>
<th>Motor outcome</th>
<th>Neuro imaging</th>
</tr>
</thead>
<tbody>
<tr>
<td>Mohapp et al. [19]</td>
<td>EEG</td>
<td>-</td>
<td>10 MI, ME</td>
<td>Hand</td>
<td>-</td>
<td>-</td>
<td>-</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>Bai et al. [20]</td>
<td>EEG</td>
<td>-</td>
<td>1 MI, ME</td>
<td>Hand</td>
<td>-</td>
<td></td>
<td>Visual</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>Bach et al. [33]</td>
<td>MEG</td>
<td>-</td>
<td>8 MI</td>
<td>Hand</td>
<td>-</td>
<td></td>
<td>Visual, orthosis</td>
<td>MRC</td>
<td>-</td>
</tr>
<tr>
<td>Ang et al. [*] [34]</td>
<td>EEG Yes</td>
<td>6,7</td>
<td>MI</td>
<td>Upper limb</td>
<td>-</td>
<td></td>
<td>Visual, robot</td>
<td>FMA</td>
<td>-</td>
</tr>
<tr>
<td>Daly et al. [36]</td>
<td>EEG Yes</td>
<td>1</td>
<td>MI, ME</td>
<td>Hand</td>
<td>-</td>
<td></td>
<td>Visual, FES</td>
<td>Finger extension</td>
<td>-</td>
</tr>
<tr>
<td>Ang et al.* [37]</td>
<td>EEG Yes</td>
<td>11,14</td>
<td>MI</td>
<td>Upper limb</td>
<td>-</td>
<td></td>
<td>Visual, robot</td>
<td>FMA</td>
<td>-</td>
</tr>
<tr>
<td>Broetz et al. [38]</td>
<td>EEG, MEG</td>
<td>1</td>
<td>MI</td>
<td>Hand</td>
<td>Yes</td>
<td></td>
<td>Visual, orthosis</td>
<td>FMA, WMFT, Ashworth, GAS</td>
<td>-</td>
</tr>
<tr>
<td>Prasad et al. [39]</td>
<td>EEG</td>
<td>5</td>
<td>MI</td>
<td>Upper limb</td>
<td>Yes</td>
<td></td>
<td>Visual</td>
<td>ARAT, GS</td>
<td>-</td>
</tr>
<tr>
<td>Ang et al. [40]</td>
<td>EEG</td>
<td>54</td>
<td>MI, ME</td>
<td>Upper limb</td>
<td>-</td>
<td></td>
<td>Visual, robot</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>Biasiucci et al. [21]</td>
<td>EEG</td>
<td>6</td>
<td>MI, ME</td>
<td>Hand</td>
<td>-</td>
<td></td>
<td>Visual</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>Caria et al.* [49]</td>
<td>EEG, MEG</td>
<td>1</td>
<td>MI</td>
<td>Hand</td>
<td>Yes</td>
<td></td>
<td>Visual, orthosis</td>
<td>FMA, WMFT, Ashworth, GAS</td>
<td>fMRI, DTI</td>
</tr>
<tr>
<td>Gomez-Rodriguez et al. [22]</td>
<td>EEG</td>
<td>2</td>
<td>MI</td>
<td>Upper limb</td>
<td>-</td>
<td></td>
<td>Visual, robot</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>Niazi et al. [23]</td>
<td>EEG</td>
<td>5</td>
<td>ME</td>
<td>Ankle</td>
<td>-</td>
<td></td>
<td>Visual</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>Shindo et al. [41]</td>
<td>EEG</td>
<td>8</td>
<td>MI</td>
<td>Hand</td>
<td>-</td>
<td></td>
<td>Visual, orthosis</td>
<td>TMS, SIAS, MAL-AOU, MAS</td>
<td>-</td>
</tr>
<tr>
<td>Sun et al. [42]</td>
<td>EEG</td>
<td>20</td>
<td>MI</td>
<td>Lower limb</td>
<td>-</td>
<td></td>
<td>Visual</td>
<td>BBS, HWC</td>
<td>-</td>
</tr>
<tr>
<td>Tam et al. [24]</td>
<td>EEG</td>
<td>5</td>
<td>MI</td>
<td>Hand</td>
<td>-</td>
<td></td>
<td>Visual, FES</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>Ang et al. [43]</td>
<td>tDCS, EEG Yes</td>
<td>3,2</td>
<td>MI</td>
<td>Upper limb</td>
<td>-</td>
<td></td>
<td>Visual, robot</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>Arvaneh et al.* [25, 26]</td>
<td>EEG</td>
<td>11</td>
<td>MI</td>
<td>Upper limb</td>
<td>-</td>
<td></td>
<td>Visual, robot</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>Buch et al.* [44]</td>
<td>MEG</td>
<td>8</td>
<td>MI</td>
<td>Hand</td>
<td>-</td>
<td></td>
<td>Visual, orthosis</td>
<td>MEG</td>
<td>-</td>
</tr>
<tr>
<td>Bundy et al. [27]</td>
<td>EEG</td>
<td>4</td>
<td>MI, ME</td>
<td>Hand</td>
<td>-</td>
<td></td>
<td>Visual</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>Cincotti et al.* [28]</td>
<td>EEG</td>
<td>29</td>
<td>MI, ME</td>
<td>Hand</td>
<td>-</td>
<td></td>
<td>Visual</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>Frisoli et al. [29]</td>
<td>EEG, Eye tracker</td>
<td>4</td>
<td>MI, Gaze</td>
<td>Upper limb</td>
<td>-</td>
<td></td>
<td>Visual, robot</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>Kaiser el at. [30]</td>
<td>EEG</td>
<td>29</td>
<td>MI, ME</td>
<td>Hand</td>
<td>-</td>
<td></td>
<td>-</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>Kasashima et al. [45]</td>
<td>tDCS, EEG</td>
<td>6</td>
<td>MI</td>
<td>Hand</td>
<td>-</td>
<td></td>
<td>-</td>
<td>FMA</td>
<td>-</td>
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<tr>
<td>Takahashi et al. [46]</td>
<td>EEG</td>
<td>1</td>
<td>ME</td>
<td>Ankle</td>
<td>-</td>
<td></td>
<td>Visual, FES</td>
<td>EMG</td>
<td>-</td>
</tr>
<tr>
<td>Arvaneh et al.* [31]</td>
<td>EEG</td>
<td>11</td>
<td>MI</td>
<td>Upper limb</td>
<td>-</td>
<td></td>
<td>Visual, robot</td>
<td>-</td>
<td>-</td>
</tr>
<tr>
<td>Mihara et al. [47]</td>
<td>NIRS Yes</td>
<td>10,10</td>
<td>MI</td>
<td>Upper limb</td>
<td>Yes</td>
<td></td>
<td>Visual</td>
<td>FMA, ARAT</td>
<td>-</td>
</tr>
<tr>
<td>Varukuti et al.* [48]</td>
<td>EEG Yes</td>
<td>6,3</td>
<td>MI</td>
<td>Upper limb</td>
<td>-</td>
<td></td>
<td>Visual, robot</td>
<td>FMA</td>
<td>fMRI</td>
</tr>
</tbody>
</table>

* Data from Ang et al. [40], Broetz et al. [38], Buch et al. [33], Biasiucci et al. [21].

intervention compared to robotic intervention for upper limb rehabilitation on 6 and 7 stroke patients, respectively. The motor outcome was clinically measured using the Fugl-Meyer Assessment (FMA) [35], and the study showed statistically significant motor outcome improvements in both groups after 12 sessions of 1-hour rehabilitation for 4 weeks, but no significant difference between groups was found. This was the first clinical study to show significant improvements in motor outcome from BCI intervention. In another study, Daly et al. [36] reported the clinical outcome of BCI for both MI and ME with functional electrical stimulation (FES) feedback intervention on 1 stroke patient, and the patient demonstrated recovery measured by increased finger extension after 9 sessions of intervention, 3 times per week for 3 weeks. Next, Ang et al. [37] updated the outcome of the RCT preliminarily reported in [34] on 11 and 14 stroke patients, respectively. Broetz et al. [38] reported a case study of using EEG and MEG-based BCI with visual and orthosis feedbacks intervention coupled with daily life-oriented physiotherapy on 1 stroke patient for a year, and motor improvements measured using a battery of assessments such as FMA, Wolf Motor Function Test (WMFT), Ashworth, 10-m Walk and Goal Attainment Score (GAS), etc. showed positive improvements. This was one of the first few studies that coupled BCI-based intervention with physical therapy. In another study, Prasad et al. [39] also reported MI BCI intervention coupled with physical therapy on 5 stroke patients, and outcome measures using Action Research Arm Test (ARAT) and grip strength (GS) showed positive improvement in at least one of the outcome measures in all the subjects.

Furthermore, Ang et al. [40] presented a study on the extent of detectable brain signals from a large population of 54 stroke patients in using EEG-based BCI to perform MI of upper limb. This study showed that a majority of but not all stroke patients could use EEG-based MI BCI, and hence suggested that a BCI screening is required to screen the stroke patient’s capability of using BCI before enrolling them for BCI-based stroke rehabilitation intervention.

Subsequently, there was an increase in the number of papers that reported clinical studies on stroke patients [41-48]. Similar to the methodology studies, we will only highlight some of these studies that we found to exhibit distinctiveness from the other studies. Caria et al. [49] presented a case report of EEG and MEG-based BCI intervention coupled with physiotherapy on a stroke patient, and showed evidence of recovery as a result of brain plasticity using DTI and fMRI. This was the first case study that showed both efficacy in terms of clinical motor improvements as well as neuroimaging. In addition, Varkuti et al. [48] reported an fMRI RCT study on 6 stroke patients who underwent MI BCI with robotic feedback compared to 3 stroke patients who received robotic rehabilitation. The results showed functional connectivity changes that were numerically higher in the group that received BCI with robotic feedback intervention. These two studies both showed brain plasticity evidence as a result from BCI intervention in stroke.

Next, Ang et al. [43] presented the preliminary result of RCT study that coupled tDCS and MI EEG-based BCI with robotic feedback intervention versus the sham-tDCS group on 2 and 3 stroke patients, respectively. The results of the study showed higher BCI accuracies from subjects who received tDCS compared to sham-tDCS, though not statistically conclusive. In a separate study, Kasahima et al. [45] also presented the result of coupling tDCS with EEG-based BCI, and demonstrated that anodal tDCS resulted in an increase in ERD of the stroke-affected hemisphere in stroke patients. The results from these two studies seem to suggest tDCS effect in modulating MI in stroke patients.

Last but not least, Mihara et al. [47] recently presented the results of an RCT on 10 stroke patients who received NIRS-based BCI with visual feedback versus 10 stroke patients who comprised the sham group and received NIRS-based BCI with irrelevant feedback. The results showed that the patients who received BCI visual feedback showed significantly greater motor improvements measured using FMA compared to the sham group. This is an important study that showed clinical evidence that BCI feedback is effective and important in BCI stroke rehabilitation.

V. DISCUSSION

BCI has attracted increased interest, especially in stroke rehabilitation. This paper reviewed the most recent works of BCI in stroke that reported on data collected from patients, and grouped the studies into methodology studies and clinical studies. Both are equally important as the former advances the technological development of BCI in stroke, and the latter demonstrates the efficacy of BCI in stroke.

Although BCI technology has the prospect of improving the lives of people with neurological disorder, or restoring motor control to stroke patients [12], there were relatively more methodology studies on healthy subjects than on stroke patients. Nevertheless, it is promising to see works that research on methods to reduce the number of EEG channels for stroke patients’ convenience while using BCI for stroke rehabilitation. In addition, many BCI methodology studies in stroke targeted the upper limb functions, and it is promising to see a few works that targeted the lower limb. Since tongue MI is one of the four MI actions detectable [32], there is also the prospect of using tongue MI for dysphagia rehabilitation.

Although there are an increasing number of clinical studies of BCI in stroke rehabilitation, there are some studies that reported both MI and ME. The dilemma is
that ME is the current practice of physical therapy and robotic rehabilitation, but BCI that muscle-activated is not strictly considered as BCI [13]. Thus the motor improvements may be the result of ME and not MI. Furthermore, it is more practical for a stroke patient with residue movements to perform AMT instead of MI. Another dilemma exists on whether to couple BCI rehabilitation with physical therapy, since study had shown that the combination yielded motor improvement of chronic stroke patients [38], but it is difficult to separate the confounding motor improvements of physical therapy from the BCI rehabilitation. An RCT study could be performed to rigorously evaluate the BCI intervention versus another intervention such as physical therapy, but RCTs are more costly and time consuming to execute [17]. Hence researchers have to consider these quandaries before conducting a clinical study of BCI in stroke.

VI. Conclusions

This paper reviewed the recent works of BCI in stroke patients specifically on methodology and clinical studies. The former focused on methods developed for and on data from stroke patients, and the latter focused on clinical studies to evaluate the efficacy of BCI in stroke. From the amount of recent works reviewed, the interest in BCI research for stroke is definitely increasing. Several challenges in the BCI for stroke rehabilitation research are discussed in this paper. Nevertheless, innovative developments are definitely forthcoming and increasing convincing clinical evidence of the efficacy of BCI in stroke will become available.

Acknowledgments


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INTERNATIONAL BRAIN-COMPUTER INTERFACE WORKSHOP AND TRAINING COURSE, Graz, Austria, 2006, pp. 80-81.


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